User Manual

Original Instructions



Guardmaster GuardLink Safety System

Catalog Numbers 440R-DG2R2T (DG Safety Relay); 440S-SF8D, 440S-SF5D, 440S-MF5D, 440S-MF8D (Taps); 898D-418U-DM2 (Terminator); 440S-ASWSBR (Bracket); 440R-ENETR (EtherNet/IP Network Interface)





Important User Information

Read this document and the documents listed in the additional resources section about installation, configuration, and operation of this equipment before you install, configure, operate, or maintain this product. Users are required to familiarize themselves with installation and wiring instructions in addition to requirements of all applicable codes, laws, and standards.

Activities including installation, adjustments, putting into service, use, assembly, disassembly, and maintenance are required to be carried out by suitably trained personnel in accordance with applicable code of practice.

If this equipment is used in a manner not specified by the manufacturer, the protection provided by the equipment may be impaired.

In no event will Rockwell Automation, Inc. be responsible or liable for indirect or consequential damages resulting from the use or application of this equipment.

The examples and diagrams in this manual are included solely for illustrative purposes. Because of the many variables and requirements associated with any particular installation, Rockwell Automation, Inc. cannot assume responsibility or liability for actual use based on the examples and diagrams.

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Throughout this manual, when necessary, we use notes to make you aware of safety considerations.



Labels may also be on or inside the equipment to provide specific precautions.



SHOCK HAZARD: Labels may be on or inside the equipment, for example, a drive or motor, to alert people that dangerous voltage may be present.



BURN HAZARD: Labels may be on or inside the equipment, for example, a drive or motor, to alert people that surfaces may reach dangerous temperatures.



ARC FLASH HAZARD: Labels may be on or inside the equipment, for example, a motor control center, to alert people to potential Arc Flash. Arc Flash will cause severe injury or death. Wear proper Personal Protective Equipment (PPE). Follow ALL Regulatory requirements for safe work practices and for Personal Protective Equipment (PPE).

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	This user manual is a reference guide for the GuardLink [™] safety system, plug-in modules, and accessories. It describes the procedures that you use to install, wire, and troubleshoot your relay. This manual explains how to install and wire your relay and gives you an overview of the GuardLink safety system
Who Should Use This Manual	Use this manual if you are responsible for the design, installation, programming, or troubleshooting of control systems that use the GuardLink safety system.
	You must have a basic understanding of electrical circuitry and familiarity with safety-related control systems. If you do not, obtain the proper training before using this product.
Summary of Changes	This manual contains new and updated information as indicated in the following table.

Торіс	Page
Updated Figure 5	20
Updated wire size	28
Updated all schematic drawings in <u>Appendix B</u>	89

Definitions

Publication <u>AG-7.1</u> contains a glossary of terms and abbreviations that are used by Rockwell Automation to describe industrial automation systems. The following is a list of specific terms and abbreviations that are used in this manual.

- Electrical Mechanical Safety Switch (EMSS) A type of tap that interfaces with safety devices that have redundant voltage-free contacts. The tap generates pulse tests to detect short circuits to the DC power supply, short circuits to the DC common, and shorts circuits between the two contacts.
- GuardLink Control, Lock, and Unlock (CLU) Signal This signal is either static or dynamic. When static, this signal is LO when the system is operational and HI when a demand is placed on the safety system. The signal is dynamic when an unlock command is issued to Power to Release guard locking devices.
- **GuardLink Operational State** All taps on the GuardLink circuit indicate that their associated safety device is ready for the machine to operate.
- **GuardLink Safe State** One or more of the taps on the GuardLink circuit indicate that their associated safety device is not ready for the machine to operate.

- **GuardLink Safety Signal** A known dynamic safety signal in operational mode and a two-way communication signal that the DG safety relay initiates to determine the status of the taps in the safe state.
- **HI** The ON state of the output of a logic block or the state of an input to a logic block or a voltage level to be above the turn-on threshold.
- LO Logic state of being OFF or a voltage level to be below the turn-off threshold.
- N/C No connection
- N.C. (Normally Closed) A voltage-free electrical contact whose normal state (that is, no pressure or electrical potential applied) is in the closed position.
- N.O. (Normally Open) A voltage-free electrical contact whose normal state (that is, no pressure or electrical potential applied) is in the open position.
- Output Signal Switching Device (OSSD)- Generally a pair of solidstate signals that are pulled up to the DC source supply. The signals are pulse-tested for short circuits to the DC power supply, short circuits to the DC common and shorts circuits between the two signals.
- **Reaction Time** The time between the true states of one input to the ON state of the output.
- **Recovery Time** The time that is required for the input to be in the LO state before returning to the HI state.
- **Response Time** The time between the trigger of one input to the OFF state of the output.
- **Safety Function** The complete process from sensing the action (for example, open a safety gate) to executing the final output device (for example, turning off a pair of contactors).
- Single Wire Safety (SWS) A unique unidirectional safety-rated signal that is sent over one wire to indicate a safety status and command the initiation of a safety function. The SWS can be used in Category 4, Performance Level e, per ISO 13849-1 and safety integrity level (SIL) 3, per IEC 62061 and IEC 61508.
- **Status Indicators** The status indicators on the front face of the DG safety relay and the taps are bicolor. <u>Table 1</u> shows how the status indicators are used in this publication.

Table 1 - Status Indicator State

Symbol	Description	Symbol	Description
	Green indicator is OFF Red indicator is OFF		Green indicator flashes with certain
	Green indicator is OFF Red indicator is ON		Red indicator is OFF
	Green indicator is OFF Red indicator flashes with certain		Green indicator is ON Red indicator is ON
	frequency		Green indicator flashes with certain frequency
	Green indicator is ON Red indicator is OFF		Red indicator flashes with certain frequency

- **Tap** A connection in a GuardLink circuit that associates a safety device to the GuardLink circuit.
- Voltage-free Contacts Electrical contacts that have no voltage that is applied to them. These contacts are typically N.O. or N.C. contacts that change state due to a mechanical (for example, someone pressing a push button) or electromechanical (for example, solenoid operated) stimulus.

Additional Resources

These documents contain additional information concerning related products from Rockwell Automation.

Resource	Description
NEMA Standard 250 and IEC 60529	Provides explanations of the degrees of protection that is provided by different types of enclosure.
Industrial Automation Wiring and Grounding Guidelines, publication <u>1770-4.1</u>	Provides general guidelines for installing a Rockwell Automation industrial system.
Product Certifications website, <u>http://</u> <u>www.rockwellautomation.com/global/certification/</u> <u>overview.page</u>	Provides declarations of conformity, certificates, and other certification details.
Industrial Automation Glossary, publication <u>AG-7.1</u>	A glossary of industrial automation terms and abbreviations.

You can view or download publications at

<u>http://www.rockwellautomation.com/global/literature-library/overview.page</u>. To order paper copies of technical documentation, contact your local Allen-Bradley distributor or Rockwell Automation sales representative.

Notes:

Overview

What Is a GuardLink System?

A GuardLink[™] system is a collection of components to simplify a series connection of safety devices while achieving the highest industrial safety rating. The system has these important features:

- Simplifies the connection of series connected safety devices.
- Facilitates the scalability of the safety series connections.
- Provides diagnostic information about each device in the system without having to run a separate status wire back to the machine control system.
- Allows the simultaneous or individual lock and unlock of guard locking interlocks in the series connected system. No need for an additional wire from the machine control system to lock and unlock the safety gate.
- Helps ease communication to the machine control system over EtherNet/IP. Communication includes sending non-safety commands to the devices and receiving status information back from the safety devices.

<u>Figure 1 on page 12</u> shows the basic components of a typical application. The GuardLink tap has M12 quick disconnect terminations to facilitate wiring with cordsets and patchcords. The DG safety relay can accommodate one or two GuardLink circuits or a combination of GuardLink and individual safety devices.

Each GuardLink circuit can accommodate up to 32 taps. The DG safety relay operates and monitors two safety contactors and has a monitored manual reset.

A typical GuardLink system consists of the following:

- One DG (dual GuardLink) Guardmaster[®] safety relay (GSR)
- One GuardLink SmartTap for each safety device
- One terminator for each GuardLink circuit
- Patchcords and cordsets
- An optional Ethernet interface



Figure 1 - Typical GuardLink System

Taps

Taps create nodes in the GuardLink circuit. A safety device is connected to each tap. Two types of taps are available:

- Taps that interface with devices having voltage-free safety contacts
- Taps that interface with devices that have OSSD signals

Each type is available in an 8-pin and 5-pin device connection version.

The taps are intended to be mounted on the machine, near the location of the device it monitors. The different types and versions can be connected in any order and can be mixed.

DG Safety Relay

The DG safety relay is the host of the GuardLink system. By using a sequence of push buttons on the front face, the DG safety relay can be configured for many types of safety applications. The DG safety relay can do the following:

- Monitor up to two GuardLink circuits, two safety devices or a combination
- Use Single Wire Safety (SWS) input and output for expansion
- Execute Stop Categories 0 or 1 (immediate and delayed outputs)
- Monitor the status of output safety devices, like contactors
- Be configured for automatic or monitored manual reset
- Be configured to initiate a lock function for guard locking with a GuardLink circuit
- Be configured to initiate an unlock function for guard locking with a GuardLink circuit

Safety Device Inputs

The DG safety device inputs can be configured in one of the following arrangements:

- One GuardLink circuit
- Two GuardLink circuits
- One GuardLink circuit and one safety device
- Two safety devices
- One safety device

The DG safety relay applies AND logic to all used inputs. Unused inputs are ignored.

Single Wire Safety (SWS) Input

The DG safety relay then applies AND logic to the SWS input if configured for use. The single wire safety input is ignored if not included in the configuration.

Output Monitoring

The DG safety relay monitors the status of external safety output devices. After all safety inputs are satisfied, the DG safety relay checks the monitoring input terminal. If 24V is present, the DG safety relay proceeds to execute the reset function.

Reset

The DG safety relay reset function can be applied one of three ways:

- Automatic reset (no connection needed)
- Monitored manual reset by a momentary push button that is connected to an input terminal
- With an Ethernet interface, the machine control system can initiate the reset function.

The DG safety relay allows both an input terminal and the machine control system to perform the monitored manual reset function. The reset signal must transition from LO to HI and back to LO within a window of 0.25...3 seconds. The reset occurs on the trailing edge. When using a programmable logic controller (PLC) to generate the reset signal, use a narrower window (0.26...2.99 s) for more reliable reset action.



ATTENTION: The reset function must not be used to start or restart the machine.

In Figure 2, the DG safety relay has one GuardLink circuit and one safety device input. The EtherNet/IP interface reports status information to the machine control system. The DG safety relay monitors the status of the two output contactors and uses monitored manual reset to energize the contactors.



Figure 2 - One GuardLink Circuit and One Safety Device

Figure 3 shows an example of a DG safety relay operating as the equivalent of a DI safety relay. In Figure 3, the DG safety relay is configured to accept two input devices, control and monitor two contactors with a manual reset input. The 440R-ENETR interface reports the status to the machine control system. The machine control system can also initiate a reset command.

Figure 3 - Two Safety Devices



GuardLink Principle of Operation

The GuardLink circuit is a continuous chain of safety devices that are connected in series with only four wires. Two wires provide power and ground to the taps and devices.

The third wire (GuardLink Safety Signal) performs the diagnostics on the taps and the devices that are connected to each tap while in the safe state. It also carries the dynamic safety signal while in an operational state.

The fourth wire (CLU) provides the lock/unlock commands to guard locking devices on the circuit.

GuardLink State

The GuardLink chain can be in one of four states:

- Initialization
- Safe
- Operational
- Fault

Initialization State

The initialization state starts when power is applied to the GuardLink circuit and ends when the GuardLink circuit enters the safe state. If no errors exist, the GuardLink circuit transitions to the safe state; the initialization state cannot transition to the operational state.

During initialization, the DG safety relay establishes and verifies the validity of the circuit by checking the following items:

- All devices set their node number
- Not more than 32 devices exist
- The firmware of the taps is compatible with the DG safety relay firmware.
- The DG safety relay detects node type and position automatically. When a 440R-ENETR interface is used, it acquires the node types and positions from the DG safety relay. The 440R-ENETR interface validates the correct type and position against the setup that is provided by the Studio 5000° Add-On-Profile (AOP). If validation is not successful, the 440R-ENETR interface reports an error.
- Validates a terminator is attached to the GuardLink circuit.

Safe State

The GuardLink safety signal commands the DG safety relay to a safe state, which turns all safety outputs OFF. The GuardLink safety signal monitors the circuit for changes of state from the taps.

The CLU signal is HI (if guard locking devices are not used) or sending a dynamic unlock signal (if guard locking devices are used). The taps indicate this state by a solid red Link indicator.

Operational State

The GuardLink operational state is described as the GuardLink safety signal that generates a specific dynamic signal to the DG safety relay and the CLU signal being LO. The state of the DG safety relay safety outputs can be OFF or ON. The state depends on the configuration, other safety device inputs, the feedback monitoring input, and the reset input.

Fault State

The DG safety relay and the taps have two fault states: recoverable and non-recoverable. When a fault occurs, the taps and DG safety relay are in a safe state. Diagnostic information is provided by the indicators. The DG safety relay also sends diagnostic information to the EtherNet/IP interface.

Recoverable faults can be cleared by cycling the faulted input devices. Nonrecoverable faults require the power to the cycled and can also require troubleshooting and correction of the fault. When an EtherNet/IP interface is used, the machine control system can issue a fault reset (equivalent to a power cycle).

GuardLink Transition from Safe State to Operational State

When the GuardLink signal is in the safe state, the DG safety relay holds the CLU signal in the high or dynamic unlocking state. The DG safety relay puts all taps in the safe state. For the GuardLink signal to return to the operational state, the DG safety relay must know that all taps are ready to go to the operational state. If the taps are ready to go, the CLU signal is set to LO.

Now that the CLU is set to LO, the last tap generates the safety signal. Each successive upstream device verifies that the previous device is in a safe state, confirms that its own device is in a safe state, and sends an inverted safe state signal to the next device.

When the DG safety relay receives the safety signal, the GuardLink circuit is in an operational state, and the DG safety relay continues with the evaluation of the other inputs, output monitoring, and reset inputs.

GuardLink Transition from Operational State to Safe State

Once an input device has a demand on its safety function, the tap stops sending the safety signal. When the DG safety relay no longer detects the safety signal, the CLU signal is set to HI to make all taps enter the safe state.

GuardLink Fault Reset Command

Devices with OSSD outputs can sometimes go to a fault state that requires power cycling. The Ethernet interface can be used to send a fault reset signal from the machine control system to individual or all devices. This reset signal cycles the power to the device connected to the specified tap.

OSSD Tap

The OSSD tap is designed to specifically interface with safety products that generate OSSD outputs. The OSSD tap does not perform testing on the OSSD signals as the input device must perform the test.

The OSSD tap is looking to see if the outputs of the connected device are energized or de-energized. If the outputs are de-energized, then the tap goes to a safe state, and the input indicator is red. If the outputs of the device are energized, then the tap shows a solid or flashing green input indicator.

If the OSSD tap inputs are not the same state for three or more seconds, then the tap enters a recoverable fault state. Both inputs must go to LO and then back to HI to recover.

EMSS Tap

The EMSS tap is designed to interface with two voltage-free contacts. The tap applies 24V to one side of the contact on both channels and looks for the 24V on the monitoring input. These contacts are pulse tested by the tap, see <u>Pulse</u> <u>Testing Functions on page 57</u> for pulse details.

The tap is looking to see if both contacts are closed or open. When the contacts open, the tap goes to a safe state, and the input indicator is red. When the contacts close, the tap goes to an operational state, which turns the input indicator either solid or flashing green.

The EMSS tap has a 10 second simultaneity window. If one contact opens, the second contact must open within 10 seconds. Similarly, if one contact closes, the second contact must close within 10 seconds. If the simultaneity window requirement is not met, the tap goes to a recoverable fault state. To recover, both contacts must be cycled open and then closed again within 10 seconds.

Guard Locking with GuardLink Systems

Only Power-to-Release guard locking devices can be connected to the GuardLink taps. When guard locking devices are connected, a 440R-ENETR interface must be used. The lock and unlock commands can only be issued to the guard locking devices through the 440R-ENETR interface.

When an unlock request is issued, the DG safety relay turns off OUT X (terminal X2) immediately and starts the off-delay timer. When the off-delay timer expires, the DG safety relay issues an unlock command to the GuardLink circuit and turns off its safety outputs (terminals 13/14 and 23/24).

When multiple guard locking devices are installed on a GuardLink system, the DG safety relay inserts a short delay between commands to each successive device to minimize the momentary inrush current to the solenoids. The device closest to the DG safety relay receives the command first. The device furthest away from the DG safety relay receives the command last.

The delay between commands is between 135...300 ms. When a few guard locking devices are used, the delay is 135 ms. As more guard locking devices are included in the circuit, the delay increases. When 32 guard locking devices are used, the delay can be up to 300 ms between each device.

Figure 4 shows an example timing diagram. The delay switch is set to position 5 (1 second delay). The first guard unlocking command starts at 1000 ms. The second unlock signal occurs at 1135 ms. The third unlock signal occurs at 1270 ms. If 32 guard locking devices are installed, the last one receives the unlock command at 10,600 ms.



Figure 4 - Unlock Command Timing Diagram

Guard Locking Application Example

<u>Figure 5 on page 20</u> shows a typical guard locking application example. The DG safety relay has four taps on the GuardLink circuit:

- First tap SensaGuard[™] integrated-latch interlock switch
- Second tap 440G-LZ guard locking interlock switch
- Third tap TLS –ZR guard locking switch
- Fourth tap SensaGuard flat-pack interlock switch

The TIME switch on the DG safety relay is set to position 9, which provides a 5 second delay to allow the motor to coast to a full stop.

The SensaGuard switches allow immediate access to the machine. Additional risk reduction measures must be provided to prevent access to the hazards during the timing period.

Because guard locking is used, a 440R-ENETR interface must be included in the application. The unlock and lock control commands are initiated by an HMI and PLC. The PLC sends the command to the 440R-ENETR interface. Over the optical bus, the 440R-ENETR interface instructs the DG safety relay to generate the unlock and lock commands through the GuardLink circuit. The DG and EM safety relays report status information over the optical bus back to the PLC through the 440R-ENETR interface.

Figure 5 - Guard Locking Application Example Schematic and Logic





Indicator	Function	Configuration ID: 0x6/	
OUT	Safety Functions		IN1
IN 1	Input Type		GuardLink
IN 2	Input Type		Not used
OUT X	Output Type		SWS
IN X	Input Mode		SWS Disabled
Reset	Reset Type		Monitored Manual
FB	Reset Assignment		SOF

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Circuit Status

The gates monitored by the SensaGuard interlock switches are closed. The guard locking switches are closed and locked. The DG and EM safety relays are OFF and ready for reset.

• Starting

Press the Reset button to energize the DG and EM safety relays. Their output contacts close. Press the Start button to start the motor via contactors K1 and K2 and energize the two immediate acting loads.

• Stopping

Press the Stop button to turn the motor and immediate acting loads off. The immediate acting loads and contactors K1 and K2 de-energize immediately, and the motor coasts to a stop. This action does not unlock the guard locking switches.

IMPORTANT The Start/Stop circuit can be replaced by an equivalent machine controlled system to start or restart the hazards after the safety system is reset.

SensaGuard Switches

Opening either SensaGuard interlock turns off the DG and EM safety relays. The EM safety relay turns off K1 and K2 immediately, and the motor coasts to a stop. With the Time switch on the DG safety relay set to 9, the 13/14 and 23/24 outputs on the DG safety relay turn off after 5 seconds. This action does not unlock the guard locking switches.

Unlock the Guard Locking Switches

Use the HMI to unlock the guard locking switches. The EM safety relay turns off K1 and K2 immediately, and the motor coasts to a stop. After 5 seconds, both the 13/14 and 23/24 outputs of the DG safety relay turn off the immediate acting loads and the guard locking switches are unlocked.

IMPORTANT The outputs of the DG safety relay (13/14 and 23/24) turn off and the unlock command occurs after the time delay expires. The immediate acting loads must remove the hazards they control quickly before you can open the gate and reach the hazard.

• Restart

Close the safety gates. If the gates were unlocked, use the HMI to initiate a lock command. Both gates are locked and the GuardLink circuit is satisfied. Press the Reset button. Press the Start button to energize the immediate acting loads and turn on the motor.

Notes:

GuardLink System Design

The design of a GuardLink[™] circuit requires knowledge of the power requirements of the input devices and the length of the link cables. A voltage drop occurs across each tap. The cumulative voltage drop determines the number of taps that can be included in the circuit.

The GuardLink system makes it easy to monitor multiple devices over long distances when multiple access points to the hazardous area are required.

The DG safety relay monitors the GuardLink system. The GuardLink system can provide diagnostic information on each access point back to the machine control system.

The GuardLink system must be designed considering these factors:

• Voltage available at each node	• Wire size
• Current flowing through each node	• Power requirements for each tap
• Cable lengths	• Safety device power requirements

The GuardLink system is designed to operate on a 24V DC system. The maximum continuous current on the link circuit must not exceed 4 A; the taps and link cables are rated for 4 A continuous.

Figure 6 on page 24 identifies three tap connections: T1, T2, and T3. The voltage and safety signals are sourced to connection J1. J2 is connected to downstream taps. J3 of each tap is connected to a safety device.



Figure 6 - Tap Connections



ltem	Description	
D1, D2, D3	Safety devices	
l ₁ , l ₂ , l ₃	Current in the link cable (A)	
I_{T1}, I_{T2}, I_{T3}	Current required by a tap (A)	
I _{D1} , I _{D2} , I _{1D3}	Current required by a safety device (A)	
L ₁ , L ₂ , L ₃	Length of link cable (m)	
R ₁ , R ₂ , R ₃	Resistance of wire (Ω)	
T1, T2, T3	Taps	
V _{J1} , V _{J2} , V _{J3}	Voltage at tap connector (V)	

System Current Calculation

The GuardLink circuit current must be calculated to determine whether a significant voltage drop occurs to a safety device.

The total system current, I_1 , is the sum of the current required by the first tap plus the current required by the device that is connected to the first tap plus the current required by the downstream circuit. The total system current must not exceed 4 A, continuous.

$$I_1 = I_{T1} + I_{D1} + I_2$$

The current in each segment of the GuardLink circuit is calculated in a similar fashion.

$$I_2 = I_{T2} + I_{D2} + I_3$$
$$I_3 = I_{T3} + I_{D3}$$

The total system current, I_1 , is therefore the sum of the device currents plus the sum of the tap currents.

$$I_1 = \Sigma I_T + \Sigma I_D$$

Voltage Drop Consideration

With the potential of using up to 32 taps and long cable lengths between taps, the voltage available to the safety devices at connector J3 must be calculated.

The voltage available to the safety device has two components:

- The voltage drop due to the wire resistance of the cables
- The voltage drop within the tap

The resistance of the recommended 18 AWG cordsets and patchcords is (0.0218 ohms/m (0.00664 ohms/ft). The wire resistance of the cordset from the power supply to tap 1 (R₁) is:

 $R_1 = 0.0218 * L_1$

The wire resistance must be considered for both the power and ground; therefore the voltage drop is multiplied by two. The voltage at connector J1 of tap T1 (V_{11}) is:

$$V_{J1} = 2 * I_1 * R_1$$

The tap has a small voltage from connector J1 to J2. The typical voltage at connector J2 (V_{12}) drop through the tap from J1 to J2 is:

 $V_{J2} = V_{J1} - (2 * 0.028V)$

The voltage available at connector J3 is dependent on the device that is connected to J3. The typical voltage drop from J1 to J3 is 0.4V when the device uses 50 mA.

$$V_{13} = V_{11} - 0.4V$$
 (typical)

IMPORTANT The voltage drop from J1 to J3 can be as high as 1.2V with a maximum load of 500 mA at the highest rated ambient temperature.

The taps consume 25 mA when OFF. The EMSS taps consume an additional 15 mA (7.5 mA per channel) when the contacts are closed. The OSSD taps consume an additional 6 mA (3 mA per channel), when the outputs are ON.

A spreadsheet can be used to calculate the voltage available to the safety device. <u>Table 4 on page 26</u> shows the voltage available to the safety device of a number of different devices. Assuming that the power supply voltage is set to 24V, and the cable is the recommended 18 AWG, the voltage available to the safety devices is shown in the right-hand column.

When guard locking devices are used in the circuit, the taps and wiring components are subjected to momentary surges in current. With the sequential operation of the lock/unlock command, the momentary surges should not adversely affect the performance of the GuardLink circuit.

The operating voltage specification of the tap is 20.4...26.4V. In the example that is shown in <u>Table 4</u>, the voltage at J1 of tap 6 has fallen below the lowest supply voltage specification of 20.4V DC. This system is not feasible, and remedial action must be taken (see <u>Table 5</u>).

IMPORTANT <u>Table 4</u> assumes the following:

- Supply voltage = 24V
- Link cable wire gauge = 18 AWG
- Link wire resistance = 0.0218 ohms/m

Table 4 - Voltage Calculation at 24V Supply

Тар	Cable Length [m (ft)]	Safety Device	Tap + Device Current (mA)	Total Current (mA)	J1 Voltage (V)	J3 Voltage Typical (V)
1	15 (49.2)	SensaGuard™ Ser A	81	1105	23.22	22.82
2	15 (49.2)	SensaGuard Ser A	81	1024	22.49	22.09
3	15 (49.2)	Lite Lock 440G-LZ	135	943	21.82	21.42
4	15 (49.2)	800F E-stop	40	808	21.25	20.85
5	15 (49.2)	LifeLine 4	40	768	20.70	20.30
6	15 (49.2)	LifeLine 5	81	728	20.19	19.79
7	15 (49.2)	TLSZR-GD2 PLe	135	647	19.73	19.33
8	15 (49.2)	TLSZR-GD2 PLe	135	512	19.36	18.96
9	15 (49.2)	Lite Lock 440G-LZ	135	377	19.10	18.70
10	15 (49.2)	SensaGuard Ser A	81	242	18.92	18.52
11	15 (49.2)	SensaGuard Ser A	81	161	18.81	18.41
12	15 (49.2)	Mechanical Switch	40	80	18.75	18.35
13	15 (49.2)	Mechanical Switch	40	40	18.73	18.33
14	0 (0)	_	0	0	_	—
15	0 (0)	—	0	0	—	—

To remedy the example in <u>Table 4</u>, the supply voltage can be increased from 24V to 26V as shown in <u>Table 5</u>. Now, all 13 taps meet the minimum voltage specification of 20.4V at connector J1.

IMPORTANT	Table 5 assumes the following:
-----------	--------------------------------

- Supply voltage = 26V
- Link cable wire gauge = 18 AWG
- Link wire resistance = 0.0218 ohms/m

Table 5 - Voltage Calculation at 26V Supply

Тар	Cable Length [m (ft)]	Safety Device	Tap + Device Current (mA)	Total Current (mA)	J1 Voltage (V)	J3 Voltage Typical (V)
1	15 (49.2)	SensaGuard Ser A	81	1105	25.22	25.82
2	15 (49.2)	SensaGuard Ser A	81	1024	24.49	24.09
3	15 (49.2)	Lite Lock 440G-LZ	135	943	23.82	23.42
4	15 (49.2)	800F E-stop	40	808	23.25	22.85
5	15 (49.2)	LifeLine 4	40	768	22.70	22.30
6	15 (49.2)	LifeLine 5	81	728	22.19	21.79
7	15 (49.2)	TLSZR-GD2 PLe	135	647	21.73	21.33
8	15 (49.2)	TLSZR-GD2 PLe	135	512	21.36	20.96
9	15 (49.2)	Lite Lock 440G-LZ	135	377	21.10	20.70
10	15 (49.2)	SensaGuard Ser A	81	242	20.92	20.52
11	15 (49.2)	SensaGuard Ser A	81	161	20.81	20.41
12	15 (49.2)	Mechanical Switch	40	80	20.75	20.35
13	15 (49.2)	Mechanical Switch	40	40	20.73	20.33
14	0 (0)	—	0	0		_
15	0 (0)	_	0	0		_

Tap Cabling

The GuardLink system was designed with the intent of minimizing wiring by using quick-disconnect patchcords, while also allowing some manual wiring to terminals, when pinout incompatibilities exist.

Figure 7 shows the recommended cable options for the various stages of a GuardLink system (to show the cable options only two taps are required, a full system has 32 taps). These cables are red-colored, PVC, unshielded, with epoxy-coated hardware. Although any color jacket can be used, the red color is preferred to indicate a safety circuit.

Visit <u>ab.rockwellautomation.com/Connection-Devices/DC-Micro-Cordsets-</u> <u>and-Patchcords</u> for other options, like right-angle connectors, stainless steel couplings, and shielded cables.

To maintain the safety integrity of the GuardLink signal, the wiring distance between taps is limited to 30 m (98.4 ft) and requires 18 AWG (0.82 mm^2) wire. If the distance between devices is greater than 30 m (98.4 ft), then a tap must be inserted at least every 30 m (98.4 ft). A field-attachable quickdisconnect can be wired as a shorting plug for the device connection. The wiring distance between taps and the safety device is limited to 10 m (32.8 ft), and requires at least 24 AWG (0.2 mm^2) wire size.





⁽¹⁾ Replace the x with 0M3 (0.3 m [0.984 ft]), 0M6 (0.6 m [1.968 ft]), 1 (1 m [3.28 ft]), 2 (2 m [6.56 ft]), 5 (5 m [16.4 ft]), 10 (10 m [32.8 ft]), 15 (15 m [9.2 ft]), 20 (20 m [65.6 ft]), or 30 (30 m [98.4 ft]) for standard cable lengths.

Terminator

The terminator (Figure 8), must be installed on the last tap to complete the link connection. The terminator contains internal electrical components specifically for a GuardLink system; other terminators cannot be used as substitutes.

Figure 8 - Terminator — Catalog Number 898D-418U-DM2



Tap Replacement

Response Time

A GuardLink tap can be replaced with the same type of tap while the link is powered. When the connections are remade; the GuardLink circuit recovers automatically.

The GuardLink circuit has a fast response time. When a safety device opens, the tap responds within 5 ms. The GuardLink safety signal then travels upstream to the DG safety relay, which takes an additional 35 μ s through each upstream tap.

Figure 9 shows an example GuardLink safety circuit with six taps. In this example, a SensaGuard rectangular flat pack interlock, which is connected to Tap 4, opens.



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The safety system response time for the system that is shown in Figure 9 is listed in Table 6. The time from when the SensaGuard interlock opens to the time when the 100S contactors drop out is 169.105 ms. The time from when the SensaGuard interlock opens to the time when the SWS signal turns OFF is 114.105 ms.

	Response Time [ms]		
Component	DG Output 13/14, 23/24	DG Output SWS (X2)	
SensaGuard ⁽¹⁾	54.0	54.0	
Tap 4	5.0	5.0	
Tap 3	0.035	0.035	
Tap 2	0.035	0.035	
Tap 1	0.035	0.035	
DG Safety Relay	60.0	55.0	
100S Contactor ⁽²⁾	50.0	0.0	
Total	169.105	114.105	

Table 6 - Example Response Time Calculation

(1) See publication <u>440N-IN008</u>.

(2) See publication <u>100-TD013</u>.

IMPORTANTFigure 9 and Table 6 show only a portion of a complete safety system.Additional time (for example, for motor stopping time and the response
time of additional components that are connected to the SWS signal) must
be considered.

Installation

The DG safety relay uses the same housing as GSR modules. The module dimensions are shown in <u>Figure 10</u>, while <u>Figure 11</u> shows the tap dimensions.

Mounting Dimensions

Figure 10 - DG Safety Relay Dimensions [mm (in.)]







DIN Rail Mounting and Removal

The DG safety relay easily mounts onto 35 mm (1.4 in.) DIN rails: 35 x 7.5 x 1 mm (1.4 x 0.3 x 0.04 in.) (EN 50022 - 35x7.5).

- 1. Hold the top at an angle (<u>Figure 12</u>).
- 2. Slide down until the housing catches the rail.
- 3. Swing the bottom down and give a little push until the latch clips onto the rail.

Figure 12 - DIN Rail Mounting



Removal

To remove the DG safety relay, use a screwdriver to pry the DIN rail latch downwards until it is in the unlatched position. Then, swing the module up.

Spacing

The DG safety relay can be mounted next to other GSR safety relays. When the GSR Ethernet interface is used, the GSR module must be mounted within 10 mm (0.39 in.) of the module next to it to maintain effective communications.

Maintain 50 mm (2 in.) of space above, below, and in front of the relay for adequate ventilation.

Terminal Block Removal and Replacement

Terminal blocks can be removed and replaced following these instructions.

Terminal Block Removal

DG safety relays have removable terminal blocks. Use a screwdriver as a lever to remove the blocks. As shown in <u>Figure 13</u>, insert the screwdriver into the slot and pry up.

Figure 13 - DG Terminal Removal



Terminal Block Replacement

The terminal blocks are keyed to help prevent a block from being inserted into an incorrect location. The orange-colored insert provides the orientation of the key (Figure 14).

Figure 14 - Orange-colored Keyway



Tap Installation

The tap can be installed directly with two M5 screws. In Figure 15, the 38.5 mm (1.5 in.) wide tap fits neatly on a standard 40 mm (1.6 in.) aluminum extrusion construction profile.





Figure 16 shows an optional quick mounting bracket, catalog number 440S-ASWSBR, is available to facilitate installation and removal. The tap snaps into place and can be easily removed to install patchcords and cordsets.

Figure 16 - Quick-release Mounting Bracket



Recessed Mounting Holes (x6)

Figure 17 shows the dimensions of the quick-release mounting bracket.

Figure 17 - Mounting Bracket Dimensions



Figure 18 shows some of the mounting options with the quick release bracket. The bracket can be mounted on various sizes of profile and can mount in-line or across the profile.

Figure 18 - Mounting Options with Quick-release Bracket



Enclosure Considerations

Consider the following when choosing your DG safety relay and tap enclosure.

DG Safety Relay

The DG safety relay is intended for use in a Pollution Degree 2 industrial environment, in overvoltage Category II applications (as defined in IEC 60664-1), at altitudes up to 2000 m (6562 ft) without derating. This equipment is considered Group 1, Class A industrial equipment according to IEC/CISPR 11. Without appropriate precautions, there can be difficulties with electromagnetic compatibility in residential and other environments due to conducted and radiated disturbances.

The DG safety relay is supplied as open-type equipment. It must be mounted within an enclosure that is suitably designed for those specific environmental conditions that are present and appropriately designed to help prevent personal injury that results from accessibility to live parts. The enclosure must have suitable flame-retardant properties to help prevent or minimize the spread of flame that complies with a flame spread rating of 5VA, V2, V1, V0 (or equivalent) if non-metallic. The interior of the enclosure must be accessible only by the use of a tool. Subsequent sections of this publication may contain additional information regarding specific enclosure type ratings that are required to comply with certain product safety certifications.

Other helpful publications can be found in <u>Additional Resources on page 9</u>.

Taps

Taps are intended to be mounted on the machine and are rated for Pollution Degree 3.

Prevent Excessive Heat

Consider the following to help prevent excessive heat for your DG safety relay and tap.

DG Safety Relay

For most applications, normal convective cooling keeps the DG safety relay within the specified operating range. Verify that the specified temperature range is maintained. Proper spacing of components within an enclosure is usually sufficient for heat dissipation.

In some applications, other equipment inside or outside the enclosure produce a substantial amount of heat. In this case, place blower fans inside the enclosure to help with air circulation and to reduce hot spots near the controller.

Additional cooling provisions can be necessary when high ambient temperatures are encountered. Do not bring in unfiltered outside air. Place the controller in an enclosure to help protect it from a corrosive atmosphere. Harmful contaminants or dirt can cause improper operation or damage to components. In extreme cases, you may need to use air conditioning to help protect against heat buildup within the enclosure.

Taps

The taps have no spacing requirements.
Power, Ground, and Wire

Wiring Requirements and Recommendation



WARNING: Before you install and wire any device, disconnect power to the system.



WARNING: Calculate the maximum possible current in each power and common wire. Observe all electrical codes that dictate the maximum current allowable for each wire size. Current above the maximum rating can cause wiring to overheat, which can cause damage.

- Allow for at least 50 mm (2 in.) between I/O wire ducts or terminal strips and the relay.
- Route incoming power to the relay by a path separate from the device wiring. Where paths must cross, their intersection must be perpendicular.
- Do not run signal or communications wiring and power wiring in the same conduit. Route wires with different signal characteristics by separate paths.
- Separate wiring by signal type. Bundle wiring with similar electrical characteristics together.
- Separate input wiring from output wiring.
- Label wiring to all devices in the system. Use tape, shrink-tubing, or other more dependable means to label wire. Use colored insulation as well to identify wiring by signal characteristics. For example, use blue for DC wiring and red for AC wiring.

DG Safety Relay

Wire Size

Each terminal can accommodate copper wire with size from 0.2...2.5 mm² (24...14 AWG). Use copper that can withstand 60/75 °C (140/167 °F).

Terminal Torque

Torque terminals to 0.4 N•m (4 lb•in).

Terminal Assignment and Function

The relays have four terminals: two on the top and two on the bottom. As shown in Figure 19, the X2 and X4 terminal markings apply to the terminals further back. The X1 and X3 terminals apply to the terminals closest to the front.

Figure 19 - DG Terminal Identification



Some of the terminals can be configured for multiple functions. <u>Table 7</u> lists the functions available for each terminal.

Table 7 - Terminal Assignments and Functions

Terminal	Function	
A1	+24V Supply (+10%, -15%)	
A2	OV Common	
S11	Pulse Test Output	
S21	Pulse Test Output	
S12	GuardLink™ Safety or Safety N.C.	
S22	GuardLink CLU or Safety N.C.	
S32	GuardLink Safety or Safety N.C.	
S42	GuardLink CLU or Safety N.C.	
X1	SWS In or OSSD In	
Х2	SWS Out or OSSD Out	
Х3	Standard Input (Feedback)	
Х4	Standard Input (Reset)	
13	Radundant Positive-Guided Relay Quitout 1	
14	nedundant i ostive-duided neray output i	
23	Daduadant Daritius Cuidad Dalau Qutaut 2	
24	neuunuani i ostive uuueu neuv uutput z	

Tap Pin Assignment and Function

Each tap has three M12 quick disconnect connectors (Figure 20). The system is designed to use premanufactured patchcords to facilitate installation, modification, and troubleshooting. The link connectors are 4-pin. The device connectors are either 5-pin or 8-pin.

Figure 20 - Tap Connection Identification



The link connections carry the power and command signals. Figure 21 shows the functions of each pin. When using Allen-Bradley[®] Guardmaster[®] patchcords and safety devices, you do not need to be concerned about the pin assignments, the system is connect and go.



<u>Figure 22</u>...<u>Figure 25</u> show the functions that are assigned to the 8-pin and 5-pin quick-disconnect connections for safety devices.

Figure 22 - J3 8-Pin OSSD (Female) Connector



Pin	Function
1	The auxiliary status output signal is not used by the tap
2	+24V Supply (+10%, -15%)
3	The Lock/Unlock command to the device
4	Safety OSSD channel B+ (24V DC)
5	Safety OSSD channel A
6	Safety OSSD channel B
7	0V DC, the reference for the 24V supply
8	Safety OSSD channel A+ (24V DC)

-	
2: Lock/Unlock Command —	— 3: Aux Contact
1: Aux Contact —	8: Safety Contact A
	4: Safety Contact B
7: 0V	
6: Safety Contact B	5: Safety Contact A

Pin	Function
1	Auxiliary (non-safety) contact
2	Lock/Unlock command
3	Auxiliary (non-safety) contact
4	24V output for safety contact channel B
5	Safety contact channel A
6	Safety contact channel B
7	0V DC, the reference for the Lock/Unlock command
8	24V output for safety contact channel A

Figure 23 - J3 8-Pin EMSS (Female) Connector





Pin	Function
1	The +24V power supply to the device
2	Safety OSSD channel A
3	OV DC, the reference for the power supply
4	Safety OSSD channel B
5	The auxiliary status signal is not used by the tap

Figure 25 - J3 5-pin EMSS (Female) Connector



Pin	Function
1	24V output for safety contact channel A
2	Safety contact channel A
3	No connection
4	24V output for safety contact channel B
5	Safety contact channel B

Bulletin 871A field-attachable quick-disconnect connectors can be used as shorting plugs during installation, troubleshooting, and for long distances. When the distance between taps exceeds 30 m (98.4 ft), a tap must be inserted into the GuardLink system at least every 30 m (98.4 ft). A shorting plug must then be added to the J3 connector. Figure 26 shows the wiring connections that are required to create a shorting plug.



Power Supply Connection

Many Bulletin 1606 power supplies are SELV, PELV, and Class 2-compliant.

DG Safety Relay

To comply with the CE (European) Low Voltage Directive (LVD), a DC source compliant with protected extra low voltage (PELV) or, under certain conditions, a safety extra low voltage (SELV) per IEC 60204-1 must power the DG safety relay.

For the USA, a PELV supply is required, per NFPA 79.

Figure 27 shows the power supply connections for the DG safety relay. Connect terminal A1 to +24V DC. Terminal A2 must be connected to the common of a 24V supply.

Figure 27 - DG Power Supply Connections



Taps

To comply with the CE (European) Low Voltage Directive (LVD), a DC source compliant with a protected extra low voltage (PELV) or, in certain circumstances, a safety extra low voltage (SELV) per IEC 60204-1 must power the tap. For IEC applications, an in-line, slow-blow 4 A fuse is recommended if the power supply can provide more than 4 A.

For the USA, a Class 2 power supply must be used. The Class 2 supply limits the current to 4 A, so an in-line fuse is not needed.

IMPORTANT In the USA, use of a 4 A fuse or circuit breaker in place of a Class 2 power supply is not acceptable.

Figure 28 shows the power connections to the power tap. Power is connected only to the first tap.



Multiple Power Supplies

When separate power supplies are used for the DG safety relay and the GuardLink circuit, the protective earth connections must be at the same point. Figure 29 shows an example wiring diagram (catalog number 1606-XLE240EN is not Class 2 compliant; catalog number 1606-XLP-95E is Class 2 compliant).

Figure 29 - Multiple Power Supplies — Ground PE at Same Point



Multiple power supplies must have one point common connection

DG Safety Relay Input Wiring

This section describes DG safety relay input wiring.

GuardLink Connections

Up to two GuardLink circuits can be connected to the DG safety relay. The GuardLink safety signal must be connected to either S12 or S32 and the GuardLink CLU signal must be connected to either S22 or S42. Figure 30 shows the connections for the GuardLink circuits; the wire colors apply when the recommended cordsets are used.

Figure 30 - GuardLink Connections



Devices with OSSD Outputs

Devices with OSSD outputs perform their own short circuit detection. The DG can be configured to accept up to two devices with OSSD signals. Connections of the OSSD outputs are shown in Figure 31.

Figure 31 - Wiring to Devices with OSSD Outputs



Voltage-free Contacts

Devices with voltage-free contacts must use the pulse testing outputs to detect short-circuit faults between the following:

- Channels
- Channels and power
- Channels and ground

<u>Figure 32</u> shows the recommended wiring for dual-channel and single-channel, voltage-free contacts. Voltage-free contacts can be connected to either Input 1, Input 2, or both inputs.

Figure 32 - Wiring to Voltage-free Contacts



Single Wire Safety

The DG safety relay has the Single Wire Safety capability to expand the safety function (both input and output).

SWS Connections

The Single Wire Safety (SWS) feature allows a safety relay to expand the safety function to additional safety relays using one wire, provided all safety relays have the same voltage supply reference.

The SWS signal is unidirectional. The signal flows from L11 to L12.

There can be many variations and combinations of series and parallel connections of the SWS. Each L11 terminal can be connected to up to ten L12 terminals.

IMPORTANT Do not connect two or more L11 terminals together.

Figure 33 shows an example wiring diagram with an SWS signal. The SWS can be connected between the DG safety relay and other relays in the GSR family (the CI, DI, DIS, EM, EMD, and SI relays). Relay 1 has a series connection to Relay 2. Relay 2 has a parallel connection to Relays 3 and 4. Relay 4 has a series connection to Relay 5. The safety relays must have a common power reference (24V common). In this example, the safety function started by Relay 1 turns off all other relays if AND logic is applied to L12 on all relays.

IMPORTANT The DG safety relay terminals are marked X2 and X1; which is equivalent to terminal L12 and L11 on other GSR relays.

Figure 33 - SWS Connection Example



24V DC Com (the relays must have a common reference)

Figure 34 shows the characteristics of SWS signal when it is active. It starts with a 1 ms pulse, followed 700 μ s later by a 500 μ s wide pulse. This waveform is repeated every 4 ms. The tolerance of all edges is $\pm 10\%$.

When inactive, the SWS signal is 0V.

Figure 34 - SWS Waveform



Safety Output Wiring

The DG safety relay has two voltage-free, safety-related outputs (terminals 13/14 and 23/24).

13/14 and 23/24 Safety Outputs

The 13/14 and 23/24 safety outputs have redundant (two) positive-guided relays that are internally connected between each terminal. An example of the wiring connections is shown in Figure 35. See <u>Specifications on page 83</u> for the voltage and current ratings of these relays.

If the voltage supply of the outputs exceeds the voltage supply of the relay, then low-voltage wiring must be separated from the high-voltage wiring.

Figure 35 - Output Connections of the DG Safety Relay



Surge Protection

Due to potentially high-current surges that occur when switching inductive load devices, such as motor starters and solenoids, the use of some type of surge suppression to help protect and extend the operating life of the relays is recommended. By adding a suppression device directly across the coil of an inductive device, you prolong the life of the outputs. You also reduce the effects of voltage transients and electrical noise from radiating into adjacent systems.

<u>Figure 36</u> shows an output with a suppression device. We recommend that you locate the suppression device as close as possible to the load device.

For outputs that use 24V DC, we recommend 1N4001 (50V reverse voltage) to 1N4007 (1000V reverse voltage) diodes for surge suppression for the OSSD safety outputs (<u>Figure 31</u>). The diode must be connected as close as possible to the load coil.

For outputs that use 120V AC or 240V AC, we recommend metal oxide varistors.

Figure 36 - Surge Protection Examples



Notes:

Configuration

The DG safety relay has two push buttons on the front faceplate. These buttons are labeled Config/Set and Sel./Save.

These push buttons allow you to do the following:

- Configure the DG safety relay to perform a safety function
- Confirm the existing safety functions
- Reset the DG safety relay
- Report the fault code

The DG safety relay has two modes of operation: run and configuration. The functions that the push buttons perform depend on the operating mode and length of time the push button is pressed.

- Short: The button is pressed less than one second.
- Long: The button is pressed for longer than three seconds, but shorter than 10 seconds.

Config/Set Push Button

Run Mode

Button Press	Function
Short	 The indicators show the configuration of the DG safety relay. Press once to see the configuration (see <u>Table 8 on page 51</u>). Press a second time to see the time delay setting (see <u>Table 9 on page 53</u>). Press a third time to see the status of the wiring terminals again (see <u>Table 11 on page 55</u>). After about 20 seconds of inactivity, the indicators revert to the wiring terminal status.
Long	The DG safety relay enters Configuration mode. The 13/14, 23/24, and X2 outputs turn OFF, if they are ON. After 60 seconds of inactivity, the indicators revert to the wiring terminal status. Changes to the configuration are not saved.
IMPORTAI	NT After changes to the hardware configuration of the DG safety relay or the GuardLink [™] circuit, power must be cycled to the DG safety relay, the GuardLink circuit, and to the EtherNet/IP interface

Configuration Mode

When you are in the configuration mode, the duration that the Config/Set button is depressed determines what the DG safety relay reveals.

Button Press	Function
Short	You can cycle through the configuration and can switch between the function of the blinking indicator. See <u>Table 8</u> for indicator descriptions.
Long	Abort the changes; you leave the configuration mode without saving the changes. The PWR/ Fault indicator flashes green at a 1 Hz rate. Upon release, the indicators revert to the wiring terminal status.

Sel./Save Push Button

Run Mode

Button Press	Function
Short	 The status indicators display the following: Alternating flashing green indicators if optical buses are active. Alternating flashing red indicators if optical buses are inactive.
Long	Nothing happens.

Configuration Mode

Button Press	Function
Short	You can jump from one configuration step to the next.
Long	The new configuration is saved.

Reset

If you press both push buttons simultaneously for longer than three seconds, the DG safety relay performs a power cycle. The same can be accomplished if you remove and reapply power to terminal A1.

Configuration Steps

Before starting to configure the DG safety relay, review the configuration functions in <u>Table 8</u>. The configuration examples in <u>Appendix B</u> help you select the correct configuration.

Status Indicator	Function	Indicator Color and Setting	Indicator Color and Setting	Indicator Color and Setting
OUT	Number of Safety Functions	Activate two Safety Functions (IN1 and IN2)	Activate one Safety Function (only IN1)	_
IN 1	Input Type IN1	Activate GuardLink Input function on IN1	Activate OSSD or EMSS Input function on IN1	_
IN 2	Input Type IN2	Activate GuardLink Input function on IN2	Activate OSSD or EMSS Input function on IN1	If only one Safety Function (IN1) is selected, the IN2 is disabled
OUT X	Output Type	Activate SWS Output on X2	Activate OSSD Output on X2	_
IN X	Input Mode	Activate SWS or OSSD Input on X1, depends on the previous step (SWS Input if OUT X is SWS Out, OSSD In out if OUT X is OSSD.)	Disable Input on X1	_
Reset	Reset Type	Manual Monitored Reset	Automatic Reset	_
FB	Reset Assignment	Reset on the Output function	Reset only on IN 1 ⁽¹⁾	Not used if Automatic Reset is selected

Table 8 - Configuration

(1) Only available if Manual Monitored Reset is selected.

1. Long press the Config/Set button.

The PWR/Fault indicator turns green and all other indicators flash red quickly, which indicates that the DG safety relay is in Configuration mode. Shortly after release of the Config/Set button:

- The PWR/Fault status indicator flashes green at 1 Hz.
- The OUT status indicator flashes the current configuration (red or green) at 1 Hz.
- The remaining status indicators are solid red, solid green, or off.
- 2. Short press the Config/Set button to change the function of the OUT status indicator.

IMPORTANT If you press the Config/Set button in these steps again, the status indicator switches back and forth between red and green.

Short press the Sel./Save button to accept and go to the next step.

3. Short press the Config/Set button to change the function on the IN 1 status indicator.

Short press the Sel./Save button to accept and go to the next step.

IMPORTANT If the IN 2 indicator is off, the function is not available in this configuration. The configuration proceeds to the OUT X indicator - go to step 5.

4. Short press the Config/Set button to change the function on the IN 2 status indicator, if available.

Short press the Sel./Save button to accept and go to the next step.

5. Short press the Config/Set button to change the function on the OUT X status indicator.

Short press the Sel./Save button to accept and go to the next step.

6. Short press the Config/Set button to change the function on the IN X status indicator.

Short press the Sel./Save button to accept and go to the next step.

7. Short press the Config/Set button to change the function on the Reset status indicator.

Short press the Sel./Save button to accept and go to the next step.

8. Short press the Config/Set button to change the function on the FB status indicator.

Short press the Sel./Save button to accept and go to the next step.

9. All indicators flash the new configuration. Use this step to confirm your configuration.

Short press the Sel./Save button to accept and go to the next step.

- 10. Now, you can verify and adjust the time delay. If the rotary switch is at position 0, all indicators (except the PWR/Fault) are off. If the rotary switch is in a position other than 0, then the bottom three indicators flash. The number of times the indicators flash is equal to the Time switch position.
- Rotate the rotary switch to the desired off-delay setting (see <u>Table 9 on</u> page 53).
- 12. When the configuration is finished, long press the Sel./Save button to save the new configuration.

The status indicators flash their configuration while the button is held down. When the button is released, the PWR/Fault status indicator flashes green twice, turns solid red for about five seconds, and then turns solid green again. Now, the other status indicators reflect the status of the wiring terminals (see <u>Table 11 on page 55</u>).

<i>ic</i> .
g/Set
ו mode)

Wait longer than 60 seconds without any additional changes.

Delay Setting

The delay is set by the 16 position switch as described in <u>Table 9</u>. The DG inputs must be opened during the delay. If the inputs close before the expiration of the delay time, the delayed output remains ON and any locked guards remain locked. If the inputs are reopened the timer restarts from zero.

Table 9 - Delay Switch Settings

Position	Delay	Position	Delay
0	Immediate	8	3 s
1	100 ms	9	5 s
2	200 ms	10	8 s
3	300 ms	11	10 s
4	500 ms	12	15 s
5	1s	13	20 s
6	1.5 s	14	25 s
7	2 s	15	30 s

<u>Table 10</u> shows how the status indicators confirm the delay setting. The bottom three indicators flash at 1 Hz. The flashing pauses for four seconds and then repeats. The number of flashes is equal to the delay switch setting.

Table 10 - Indicators Confirm Delay Setting

Indicator	Color	Status
PWR/Fault	*	Configuration mode
OUT		—
IN 1		_
IN 2		—
OUT X		_
IN X	*	The number of flashes
Reset	*	setting. For example: 0 = no flashing
FB	*	5 = five flashes

Verification

You can verify the configuration of the DG safety relay in three ways:

- The push buttons on the front of the DG safety relay
- The 440R-ENETR interface web page
- The Add-on-profile (AOP) in the Studio 5000° environment

Push Buttons on the Front of DG Safety Relay

While in the Run mode, short presses of the Config/Set button can verify the configuration.

IMPORTANT The PWR/Fault indicator remains green through these steps.

1. Short press the Config/Set push button.

The indicators show the configuration. Compare the colors of each indicator to your desired colors.

2. Short press the Config/Set push button again.

The indicators show the Time switch setting. If the indicators are off, then the TIME is set to zero. For a setting other than zero, the bottom three indicators flash green. The number of flashes is equal to the switch setting. The flashing pauses for four seconds and then repeats.

3. Short press the Config/Set push button one last time to return to the running status indication.

440R-ENETR Interface Web Page

Each configuration is assigned a unique identification. The ID appears as a hexadecimal value in the Config field on the web page in the DG Input Data section. See <u>440R-ENETR Interface Web Page on page 79</u> for more information. After the initial configuration, record the Config value. This value can then be compared in the future to detect changes.

AOP in the Studio 5000 Environment

Each configuration is assigned a unique identification. The ID appears as a decimal value in the Config field in the Controller Tags. See <u>Studio 5000 Code</u> <u>Examples on page 78</u> for more information. After the initial configuration, record the Config value. This value can then be compared in the future to detect changes.

Status Indicators

DG Safety Relay Status Indicators

<u>Table 11</u> describes the status of the DG safety relay status indicators during normal operation.

Table 11 - DG Indicators during Normal Operation

Indicator State Description		
	OFF	No power
	Solid Red	DG safety relay is in self-test state or idle state
PWR/Fault	Solid Green	Normal operation (Run mode)
	Flashing Green 1 Hz	Configuration mode - proceed with configuration
	Flashing Red 1 Hz	Fault Mode - Press the Sel./Save Button to see the fault code
OUT	Green	Output circuits at 13/14 and 23/24 are closed
001	Red	Output circuits at 13/14 and 23/24 are open
	Green	Input circuits at S12 and S22 are closed
IN 1	Red	Input circuits at S12 and S22 are open
	Flashing Red 1 Hz	Input signal missing or incorrect configuration
	Green	Input circuits at S32 and S42 are closed
IN 2	Red	Input circuits at S32 and S42 are open
IIN Z	Flashing Red 1 Hz	Input signal missing or incorrect configuration
	OFF	Input circuit is disabled
	Green	OSSD output/SWS output at X2 is ON
001 X	Red	OSSD output/SWS output at X2 is OFF
	Green	Input circuit at X1 closed
IN X	Red	Input circuit at X1 open
	OFF	Input circuit is disabled
	Green	Reset button at X3 pushed
Reset	Flashing Green 1 Hz	Reset at X3 required
	Red	Reset at X3 held ON. Try resetting again.
ER	Green	Feedback circuit at X4 closed
FD	Red	Feedback circuit at X4 open

Tap Status Indicators

<u>Figure 37</u> shows the location of the two tap indicators: one for the input device connection and one for the link connection. <u>Table 12</u> provides a description of the status for each indicator.

Figure 37 - Tap Indicators



Table 12 - Tap Indicators

Indicator	State Description	
	Solid Green	The input device is in the operational state with no demand on its safety function (for example, the OSSD inputs are ON or safety contacts are closed). The tap is also in the operational state.
Innut	Flashing Green at 1 Hz	The input device is in the operational state (no demand on its safety) and the tap is in the safe state. One or more upstream taps are in a safe state. The CLU signal is high, so all taps are in the safe state.
mput	Solid Red	OSSD inputs are OFF or safety contacts are open. The input device is in the safe state (for example, OSSD inputs are OFF or safety contacts are open), and there are no faults with the tap.
	Flashing Red at 1 Hz	The input device has not performed as expected; for example, both inputs did not change simultaneously. Try cycling the input device again. Cycle power to GuardLink™ circuit if necessary.
	Solid Green	The tap is transmitting the safety signal.
	Solid Red	GuardLink safety signal is OFF. Or terminator is missing.
Link	Flashing Red at 1 Hz	Fault at tap or input device. Correct fault and cycle power to the GuardLink system.
	Off	No communication to DG safety relay. Input is configured for OSSD/ EMSS; recheck the configuration. Input is in faulted state. Correct fault and/or cycle power to the DG safety relay and GuardLink circuit.

Figure 38 shows an example with five taps. The device at Tap 3 has tripped, and the GuardLink safety signal is in a safe state. To locate the tripped device, follow the blinking green lights to the tap with the solid red device indicator. The link indicator is solid red, which indicates a safe (OFF) state.

Figure 38 - Tripped Device with Solid Red Status Indicators



Pulse Testing Functions

Your DG safety relay uses pulse testing of inputs with voltage free contacts to detect short circuit conditions. The test pulses are used to detect three short circuit conditions:

- Between the input terminals and +24V
- Between the input terminals and 24V common
- Between the two input terminals.

Pulse testing for the inputs must be used with devices like E-stop push buttons, tongue operated interlock switches, and limit switches that have voltage-free contacts.

The pulse-testing cannot be turned on or off and cannot be changed. Therefore, the purpose of this chapter is informational, but it can be used during troubleshooting of a DG safety circuit.

Pulse Testing for Inputs

Pulse tests for the inputs are generated on terminals S11 and S21 of the DG safety relay.

Figure 39 shows the pulse testing that is associated with the DG safety relay. The pulse widths are either 300 μ s or 600 μ s wide, and the pulses are repeated every 15 ms.

Figure 39 - Pulse Test Sequence for DG Safety Relay



EMSS SmartTap Pulse Tests

The EMSS SmartTap generates pulse tests to detect short circuit conditions. The waveforms are shown in <u>Figure 40</u>. The pulses are 1 ms wide. Channel 2 pulse occurs 8 ms after Channel 1. The pulses are repeated every 21 ms. When either of the input channels goes to an open state, the pulses are turned off.



Figure 40 - EMSS Test Pulses

Opto-link Communications

Optical Bus

The GSR family of relays use an optical bus to communicate status information to the 440R-ENETR Guardmaster[®] Ethernet/IP network interface⁽¹⁾. DG safety relays have two optical buses:

- Bus 2 allows communication to pass from the 440R-ENETR interface to the DI, DIS, EM, EMD. GLP, GLT, and SI safety relays (the CI safety relay does not have an optical bus).
- Bus 3 is used exclusively by the DG safety relay for GuardLink[™] communications.

The optical bus ports are on each side of the housing, as shown in Figure 41.



Figure 41 - Optical Bus Ports

⁽¹⁾ See publication <u>440R-UM009</u> for detailed 440R-ENETR interface information.

Arrangement with 440R-ENETR Interface

Each 440R-ENETR interface can communicate with up to six GSR relays, in any combination. All DG safety relays must be located closest to the 440R-ENETR interface, as shown in Figure 42.

Figure 42 - 440R-ENETR Interface Arrangement



The 440R-ENETR interface can monitor up to six relays of any combination. 5 mm (0.2 in.) max The DG safety relays must be closest to the 440R-ENETR interface. spacing between relays

440R-ENETR Network Interface Add-on Profile

Status and control signal can be sent from the DG safety relay to the machine control system over EtherNet/IP by using the 440R-ENETR network interface.

Add-on Profile (AOP)

To use the 440R-ENETR network interface in a Logix Designer project, you must download and install the AOP. Download firmware and associated files (such as AOP, DTM, and EDS) from <u>compatibility.rockwellautomation.com/</u><u>Pages/home.aspx</u>.

The DG safety relay is included with the release of Series B.

Add a 440R-ENETR Interface to the Project

With the AOP downloaded and installed, <u>Figure 43</u> shows the beginning steps to add the 440R-ENETR interface to the I/O Configuration.

- 1. Right-click the Ethernet identifier.
- 2. Click New Module.

Figure 43 - Controller Organizer



The Select Module Type window appears (Figure 44).

- 3. Find the 440R-ENETR. You can search, filter, or scroll to find it.
- 4. Click Create to add the module to the project.

Figure 44 - Select Module Type

Ente	er Search Text for Module Ty	Clear Filters		Hide Filters	*
ম	Module Type Category Fil	ters 🔺 🔽 Module Type \	endor Filters		
N	Communication	Allen-Bradley			
	Communications Adapter	Endress+Hause	at a second s		_
	Controller	FANUC CORPO	RATION		
	Digital	🛛 🗖 🖬 FANUC Roboti	s America		
7	DDI to DI D Ethomot /ID			[۲,
•	Catalog Number 193-DNENCAT	Description Ethernet to DeviceNet Communications Auxiliary	Vendor Allen-Bradley	Category Communication	•
	193-DNENLAT	Ethernet to DeviceNet Communications Auxiliary	Allen-Bradley	Communication	
	AAOD.ENETD	Exhemet to Device Net Communications Advinary, 24-on	Allen-Bradley	Communication	
	Drivelogiy5730 Ethernet	10/100 Mbps Ethernet Port on Drivel onix5730	Allen-Bradley	Communication	3
	F1 Plus	Electronic Overload Belay Communications Interface	Allen-Bradley	Communication	
	EtherNet/IP	Soft origination of the State of the Soft or Soft	Allen-Bradley	Communication	_
•۱	FTHERNET.RRIDGE	Generic FiherNet/IP CIP Rridge	Allen.Rradleu		Ţ
				Add to Enuo	1

The New Module window opens that shows the General information (Figure 45).

- 5. Verify that the Series, Revision, Electronic Keying, and Connection are as shown (or later).
- 6. Enter a name.
- 7. Enter a description (optional).
- 8. Select an IP address.
- 9. Click Change to add GSR relays to the project.

Figure 45 - New Module - General Tab

. New Module		×
General*	General	
Connection		1
Module Info		
Internet Protocol	Type: 440R-ENETR Guardmaster Safety Relay Ethernet Interface	
Port Configuration	Vendor: Allen-Bradley	
Network	Parent: Local Ethernet Address	
	Name: 6 ENETR_SER_B C Private Network: 0 192.168.1.	
	Description: GSR Ethernet Module Series B A	
	Module Definition	
	Series: 5 B Safety Relay 1: Undefined 9 Change	
	Revision: 2.001 Safety Relay 2: Undefined	
	Electronic Kaulan Compatible Medule Sofety Belay 2: Undefined	
	Liectonic reging. Compatible Hodels Salicty Relay 5. Childrined	
	Connection: Data-GuardLink Safety Relay 4: Undefined	
	Safety Relay 5: Undefined	
	Safety Relay 6: Undefined	
1		
Status: Creating	OK. Cancel Help]

Add Relays to the 440R-ENETR Interface

Figure 46 shows the module definition and the steps necessary to add relays that the 440R-ENETR interface monitors.

- 1. Right-click Relay Bus.
- 2. Click Add Device.
- 3. Click one of the devices in the list that appears. You can select multiple devices, but the DG safety relays must be together and closest to the 440R-ENETR interface. For this example, click the DG safety relay.

Figure 46 - Module Definition - Add a DG Safety Relay

Module Definition					×
Upload		Rela	y Bus		
🗉 🚺 440R-ENETR	2				
	Add Device ►	GSR DI	440R-D22R2		
		GSR DIS	440R-D2252		
		GSR DG	440R-DG2R2T ★		
		GSR SI	440R-512R2	- 3	
		GSR EM	440R-EM4R2	_	
		GSR EMD	440R-EM4R2D		
		GSR GLP	440R-GL252P		
		GSR GLT	440R-GL252T		
_	-			-	

In <u>Figure 47</u>, the DG safety relay has been added to Slot 1 (the relay next to the 440R-ENETR interface). Each DG safety relay can have up to two GuardLink[™] connections. By default, both GuardLink connections are disabled.



Module Definition*		×
Upload	440R-DG2R2T	
□ 🖞 440R-ENETR	Module:	440R-DG2R2T
□ i [1]440R-DG2R2T	Description:	Guardmaster Safety Relay Dual Input Relay Outputs with GuardLink
	Slot:	
	GuardLink 1 Size:	Disabled
	GuardLink 2 Size:	Disabled

Now, you can add a tap to the GuardLink connection (Figure 48 on page 64).

4. Right-click a GuardLink connection.

IMPORTANT A GuardLink connection can be added to either [1] or [2] or both.

- 5. Click Add Device.
- 6. Click the desired tap. The type of tap must be the same as the physical location of the selected tap. In this example, select the OSSD 8-pin.



м	odule Definition*		×
	<u>U</u> pload	[1]GuardLink	
	□ (1) 440R-ENETR □ \$\$\$\$ Relay Bus □ (1) 440R-DG2R2T \$\$\$111 GuardLink 5		
	💑 (2) GuardLink <u>Add Device</u> I	Diagnostic Tap - OSSD, 5-pin Diagnostic Tap - OSSD, 8-pin Diagnostic Tap - EMSS, 5-pin Diagnostic Tap - EMSS, 8-pin	405-SF5D 4405-SF8D 4405-MF5D 4405-MF8D
	4		

In <u>Figure 49</u>, the OSSD 8-pin is Node 1 (7). This tap is electrically closest to the DG safety relay.

Figure 49 - Tap 1 Is Defined as Node 1

Module	Definition*			×
Up	load	440S-SF8D		
	440R-ENETR 3 뷺 Relay Bus	Module:	4405-5F8D	
	 ☐ [1] 440R-DG2R2T □	Description:		
	<mark>[1] 440S-SF8D</mark> 쁆 [2] GuaidLink	Node:	7 1	
			_	

Repeat the steps 4...6 to add as many modules that exist in the GuardLink chain. Remember that the order of the types of modules must be the same as the physical taps.

Repeat the process for the second GuardLink chain, if a second GuardLink chain is used. If not, then the second input (terminals S32 and S42) automatically configures for one safety device during the configuration process.

Change the Order of the Devices

IMPORTANT The nodes must be sequential and must not have any gaps in the positions.

The order of the devices can be modified in one of two ways.

• Change the node value to a number greater than the last node. In Figure 50, node 4 can be changed to node 8 or higher.

Figure 50 - Node Change



• Right-click the device and click Delete Device as shown in <u>Figure 51</u>. A confirmation window appears. Click Yes to confirm delete.

Figure 51 - Node Delete

1odule Definition*		×
Upload	440S-SF5D	
□ 🖞 440R-ENETR	Module: 4405-5F5D	
□ 1 [1] 440R-DG2R2T □ 1 [1] GuardLink	Description:	
≪ [2] 440S-SF8D ≪ [2] 440S-SF5D ≪ [3] 440S-MF5D	Node: 4	
4 [4] 440S-SF5D 4 [5] 440S Delete Device		
≪ [6] 440S-MF8D ≪ [7] 440S-MF8D		
団 器 [2] GuardLink	RSLogix 5000	
	Delete the device [4] 4405-SF5D'?	
	Yes No	

Once deleted, node 4 is empty. The node must be refilled with a module, or the higher numbered nodes must be renumbered to remove empty position.

When the nodes are established, click the OK button and confirm the module change by clicking Yes as shown in <u>Figure 52</u>.

Figure 52 - Confirm Module Change

Module Definition*		×
Upload	440S-TF8D4	
□	Module:	4405-TF8D4
ভ ដ [1] 440R-DG2R21 ⊡ ដ [1] GuardLink ≪[1] 440S-SF8D	Description:	
4 [2] 440S-SF5D [3] 440S-MF5D	Node:	5 💌
Logix Designer		X
These changes will cause mor Data will be set to default val Verify module properties befor Change module definition?	lule data types and prop ues unless it can be reco rre Applying changes.	erties to change. vered from the existing module properties.
	Yes N	o
J		OK Cancel Help

You return to the General tab. Use the Change button to add up to six relays. Figure 53 shows an example with three relays. Notice that the DG safety relays are listed first.



- General* - Connection	General	
– Module Info – Internet Protocol – Pott Configuration – Network	Type: 440R-ENETR Guardmaster Safety Relay Ethernet Interface Verdor: Allen-Bradley Parent: Local Name: Ethernet Address: Description: GSR Ethernet Module Series 8	
	Module Definition Series: B Safety Relay 1: 440R-DG2R2T Electronic Keying: Compatible Module Safety Relay 2: 440R-DG2R2T Electronic Keying: Compatible Module Safety Relay 3: 440R-EMMR2 Connection: Data-GuardLink Safety Relay 4: Undefined Safety Relay 5: Undefined Safety Relay 6: Undefined	
Status: Offline	OK Cancel Apply Help	

Controller Tags

When the Ethernet interface is added to the project, the tags that are shown in Figure 54 appear in the Controller Tags section of the Studio 5000° project. The Ethernet interface has both Input and Output tags. Notice the three relays match the example from Figure 53.

See publication <u>440R-UM009</u> for more information on Ethernet interface tags. The DG safety relay tags are described in detail in <u>Table 13 on page 68</u>.

Figure 54 - Ethernet Interface Tags



Select Lock Command

Figure 55 shows how to select the Lock Command for an individual tap.

- 1. Expand the Ethernet module output.
- 2. Expand the relay output.
- 3. Expand the GuardLink output.
- 4. Expand the LockCmd selections.
- 5. Click the desired tap.

Figure 55 - Select Lock Command

γ.	Ente	Nan	ne l	1					-	Show:	All Tag	js			•
	Nam	/	-	_							28	Data Type	Usage	Description	^
1	±-5	ETR	_SE	R_B:	1			2				AB:440R_ENE	<controller></controller>		
Ī	E	IETR	_SE	R_B:	0	_	- 1	۷				AB:440R_ENE	<controller></controller>		
Ū	Ė	ENE	TR_	SER	_B:0	.Rel	ay1					AB:GSR_DG:			
1		E	NET	R_SE	ER_E	3:0.1	Rela	y1.R	eset1			BOOL			
Ū		E	NET	R_SE	ER_E	3:0.1	Rela	y1.R	eset2			BOOL			
Ī		E	NET	R SI	- P_	.0.	Rela	y1.F	aultReset			BOOL			
Ū		ė.	NET	R_SE	ER_E	3:0.1	Rela	y1.G	uardLink1			AB:GSR_DG			-
Ī			EN	ETR_	SEF	₹_B:	O.R	elay1	1.GuardLink1.Unlo	ckCmd		DINT	4		-
Ľ	ENETR_SER_B:O.Relay1.GuardLink1.LockCmd														
1	0	1	2	3	4	5	6	7	.GuardLink1.Faul	tResetCmd		DINT			
1	8	9	10	11	12	13	14	15	uardLink2			AB:GSR_DG			
1	16	17	18	19	20	21	22	23				BOOL	<controller></controller>		
1	24	25	26	27	28	29	30	31				BOOL	<controller></controller>		
	5														

Table 13 - DG Safety Relay Tags

Name	Data Type	Definition
SafetyInput01	BOOL	Safety Input 1 Status - Indicates whether safety input circuit 1 is On or Off.
		0 = The input channel is Off.
SafetyInnut02	BOOL	1 = Πε Πρυί Challiel IS OII. Safaty Input 2 Status - Indicates whether safaty input circuit 2 is Ωn or Off
Saletyinputoz	DOOL	0 = The input channel is Off.
		1 = The input channel is On.
PtS12	BOOL	S12 Status - Indicates whether terminal S12 of circuit IN01 is On or Off.
		0 = The terminal is Off. 1 = The terminal is Off.
PtS22	BOOL	S22 Status - Indicates whether terminal S22 of circuit INO2 is On or Off
	5002	0 = The terminal is Off.
		1 = The terminal is On.
PtS32	BOOL	S32 Status - Indicates whether terminal S32 of circuit INO2 is On or Off.
		0 = 1 he terminal is Off. 1 = The terminal is On.
PtS42	BOOL	S42 Status - Indicates whether terminal S42 of circuit INO2 is On or Off.
		0 = The terminal is Off.
		1 = The terminal is On.
PtS11	BOOL	S11 Status - Indicates whether terminal S11 is On or Off.
		1 = The terminal is On.
PtS21	BOOL	S21 Status - Indicates whether terminal S21 is On or Off.
		0 = The terminal is Off.
D+V1	POOL	1 = The terminal is Un.
PtXI	BUUL	A I Status - Indicates whether terminal X I is Un or Uff. 0 — The terminal ic Off
		1 = The terminal is On.
PtX2	BOOL	X2 Status - Indicates whether terminal X2 is On or Off.
		0 = The terminal is Off.
D+Y3	BOOL	1 = THE LEMINIA IS ON. X3 Status - Indicates whether terminal X3 is On or Off
1 (72)	DOOL	0 = The terminal is Off.
		1 = The terminal is On.
PtX4	BOOL	X4 Status - Indicates whether terminal X4 is On or Off.
		0 = The terminal is Off. 1 = The terminal is On
Pt13 14	BOOL	13/14 Status - Indicates whether output relays contacts at terminals 13/14 are closed or open.
		0 = The contacts are open.
	20.01	1 = The contacts are closed.
Pt23_24	BOOL	23/24 Status - Indicates whether output relays contacts at terminals 23/24 are closed or open.
		1 = The contacts are closed.
ResetRequired1	BOOL	Reset Required Indication - This indication turns On (1) when all monitored input conditions are On and the safety relay Output is
	2001	Off (0) on GuardLink circuit 1.
ResetHeldOn1	BOOL	Reset Held On Fault - Indicates that the reset signal for IN1 was held On (1) for longer than the maximum time of 3000 ms.
		1 = Fault
NonRecoverableFault	BOOL	Non-Recoverable Fault Status - Indicates whether the DG safety relay has detected unexpected internal operation.
		0 = No fault
[]t	0001	1 = Fault
Fault	BUUL	Fault Status - Indicates whether the DG safety relay has detected unexpected operation of a monitored safety device. $0 - N_0$ fault
		1 = Fault
FaultCode	INT	Fault Code - When a fault occurs, the DG safety relay generates a value to help indicate the potential cause of the fault. See
Config		<u>lable 18 on page /4</u> for a list of fault codes.
ValuePotarySwitch		Configuration in 2 - cach configuration of the DG safety relay has a unique ID. This tag determines if the configuration changed.
Guardl ink1		Guard instance of notary switch - the bolsalety reasy provides a unique value of each position of the timer foldry switch.
GuardLink2	AB:GSR DG GL:I:0	GuardLink2 Input and Output
· · ·		

Table 14 shows the tags for GuardLink1. These tags apply to input IN1, which is wiring terminals S12 and S22. GuardLink2 has the same tags, but the tags apply to input IN2, which is wiring terminals S32 and S42.

Name	Data Type	Definition	Definition							
Active	BOOL	Active Status - Ind 0 = IN1 is used for 1 = IN1 is used as	Active Status - Indicates whether the GuardLink circuit is used on IN1. 0 = IN1 is used for standard OSSD or EMSS inputs. When the Active value is zero, all remaining GuardLink tags are zero. 1 = IN1 is used as a GuardLink input.							
Tripped	BOOL	Tripped Status - In 0 = Operational 1 = Tripped	Tripped Status - Indicates whether the GuardLink circuit is operational or in a tripped state. 0 = Operational 1 = Tripped							
DiagnosticActive	BOOL	Diagnostic Active - 0 = All GuardLink 1 = One or more G for more informati	Diagnostic Active - Indicates whether the GuardLink circuit is in a diagnostic state. 0 = All GuardLink taps are not in a faulted (diagnostic) state. 1 = One or more GuardLink taps are in a faulted (diagnostic) state. The tap indicators are flashing red. See <u>Table 19 on page 74</u> for more information.							
DiagnosticCode	SINT	Diagnostic Code -	Diagnostic Code - See <u>Table 19 on page 74</u> for more information.							
Fault	BOOL	Fault - Indicates w 0 = No Fault 1 = Fault	Fault - Indicates whether the GuardLink circuit is in a fault state. See <u>Table 17 on page 71</u> for more information. 0 = No Fault 1 = Fault							
FaultCode	SINT	Fault Code - Indica	tes the fault code	when the GuardLink	circuit is faulted. See	<u>Table 17 on page 71</u> .				
DeviceTrip	DINT	Device Trip - When value that reflects With four operatio tripped, the decim	Device Trip - When all nodes are operational, DeviceTrip is the same as DeviceCount. When nodes are tripped, DeviceTrip shows a value that reflects all nodes that remain operational. Bit values of zero indicate the nodes that are tripped. With four operational nodes, the decimal value is 15. If nodes 1 and 3 are tripped, the decimal value is 10. If only node 2 is tripped, the decimal value is 13.							
		Status	Decimal	Bit 3	Bit 2	Bit 1	Bit 0			
		All Operational	15	1	1	1	1			
		Nodes 1 and 3 tripped	10	1	0	1	0			
		Node 2 tripped	13	1	1	0	1			
DeviceDiagnostic	DINT	Device Diagnostic 0 = No nodes are i	Device Diagnostic - Indicates the nodes whose diagnostics are active. 0 = No nodes are in diagnostics.							
DeviceFault	DINT	Device Fault - India 0 = No nodes are fFor example with	Device Fault - Indicates the nodes that are faulted 0 = No nodes are faulted. For example with four nodes, a 6 means that node 1 and node 4 are faulted.							
DeviceCount	DINT	Device Count - Pro For example, a 15	Device Count - Provides the number of nodes in the GuardLink1 circuit. For example, a 15 means the GuardLink system has four nodes.							

Table 14 - GuardLink 1 Tags

<u>Table 15</u> shows the 440R-ENETR interface input tags. These tags are read only and provide status of the communications to the Ethernet interface.

Table	15 -	440R-	ENETR	Interface	Input	Tags
-------	------	-------	-------	-----------	-------	------

Name	Data Type	Definition
ConnectionFaulted	BOOL	Connection Faulted - Indicates whether the connection to the Ethernet interface has faulted. 0 = No connection fault. 1 = Connection has faulted.
EthernetLink1Sts	BOOL	Ethernet Link1 Status - Indicates whether Link1 of the Ethernet interface is active. 0 = Link1 is not active. 1 = Link1 is active.
EthernetLink2Sts	BOOL	Ethernet Link2 Status - Indicates whether Link2 of the Ethernet interface is active. 0 = Link2 is not active. 1 = Link2 is active.
OpticalLinkSts	BOOL	Optical Link Status - Indicates whether Optical Links from the Ethernet interface to the GSR relays are active. 0 = Optical Link is not active. 1 = Optical Link is not active.
OpticalLink2Sts	BOOL	Optical Link2 Status - Indicates whether Optical Link2 from the Ethernet interface to the GSR relays is active. 0 = Optical Link2 is not active. 1 = Optical Link2 is not active.
OpticalLink3Sts	BOOL	Optical Link3 Status - Indicates whether Optical Link3 from the Ethernet interface to the GSR relays is active. 0 = Optical Link3 is not active. 1 = Optical Link3 is not active.
Relay1Connected	BOOL	Relay 1 Connected - Indicates whether a GSR relay is connected to the Ethernet interface via the optical link. 0 = Relay 1 is not connected. 1 = Relay 1 is connected.
Relay2Connected	BOOL	Relay 2 Connected - Indicates whether a GSR relay is connected to the Ethernet interface via the optical link.0 = Relay 2 is not connected.1 = Relay 2 is connected.
Relay3Connected	BOOL	Relay 3 Connected - Indicates whether a GSR relay is connected to the Ethernet interface via the optical link. 0 = Relay 3 is not connected. 1 = Relay 3 is connected.
Relay4Connected	BOOL	Relay 4 Connected - Indicates whether a GSR relay is connected to the Ethernet interface via the optical link. 0 = Relay 4 is not connected. 1 = Relay 4 is connected.
Relay5Connected	BOOL	Relay 5 Connected - Indicates whether a GSR relay is connected to the Ethernet interface via the optical link. 0 = Relay 5 is not connected. 1 = Relay 5 is connected.
Relay6Connnected	BOOL	Relay 6 Connected - Indicates whether a GSR relay is connected to the Ethernet interface via the optical link. 0 = Relay 6 is not connected. 1 = Relay 6 is connected.

The Ethernet interface can send commands to each of the relays that are included in the opto-links. <u>Table 16</u> lists the tags for Relay 1, where Relay 1 is a DG safety relay. Output tags for other GSR relays can be found in publication <u>440R-UM009</u>.

Table 16 - Ethernet Output Tags for Relay 1

Name	Data Type	Definition
Reset	BOOL	Reset 1 - Applies a reset command to the inputs to input IN1. 0 = Clears the reset.
		1 = Initiates a reset.
FaultReset	BOOL	Fault Reset - Applies a reset command to the DG safety relay when a faulted state exists.
		0 = Clears the reset.
		1 = Initiates a reset.
GuardLink1	AB:GSR_DG_GL:0:0	GuardLink1 - This field contains three commands (Lock, Unlock, and Fault Reset) that can be sent to the GuardLink1 circuit of the DG safety relay.
GuardLink1.UnlockCmd	DINT	Unlock Command - Can be used to send unlock commands to one or more guard locking interlocks.
GuardLink1.LockCmd	DINT	Lock Command - Can be used to send lock commands to one or more guard locking interlocks.
GuardLink1.FaultResetCmd	DINT	Fault Reset Command - Can be used to send fault reset commands to one or more guard locking interlocks. This tag must be used when the guard locking interlock has faulted. The command cycles power to the interlock.
GuardLink2	AB:GSR_DG_GL:0:0	GuardLink2 - This field contains three commands (Lock, Unlock, and Fault Reset) that can be sent to the GuardLink2 circuit of the DG safety relay. See the description for <u>GuardLink1</u> .

<u>Table 17</u> lists the fault codes for the DG safety relay.

Table 17 - DG Safety Relay Fault Codes

Fault Codes	Туре	Name	Description
0x0001	Recoverable	Test Out A stuck at	Stuck @ 24V S11
0x0002	Recoverable	Test Out B stuck at	Stuck @ 24V S21
0x0003	Recoverable	Power Fault	A1 is over 27V and under 20V
0x0004	Non-recoverable	VCC Fault	3.3V is out of range
0x0006	Non-recoverable	Internal hard fault	Summary of all faults
0x000A	Non-recoverable	Relay Contacts End of Life	Force guided relay feedback error
0x000D	Recoverable	Test Out Cross Fault	Shortcut between S11 and S21
0x0010	Non-recoverable	Terminal Fault S11	Terminal issue when configured as output like Test Out A
0x0011	Non-recoverable	Terminal Fault S21	Terminal issue when configured as output like Test Out B
0x0013	Non-recoverable	Terminal Fault S22	Terminal issue when configured as Guardlink
0x0015	Non-recoverable	Terminal Fault S42	Terminal issue when configured as Guardlink
0x0017	Non-recoverable	Terminal Fault X2	Terminal issue when configured as OSSD/SWS
0x0040	Recoverable	GuardLink-CH[0] no Termination	No terminator detected
0x0041	Recoverable	GuardLink-CH[1] no Termination	No terminator detected
0x0042	Recoverable	GuardLink-CH[0] not wired	No IAH responses
0x0043	Recoverable	GuardLink-CH[1] not wired	No IAH responses
0x0044	Recoverable	GuardLink-CH[0] more than 32 slave devices	More than 32 slave devices
0x0045	Recoverable	GuardLink-CH[1] more than 32 slave devices	More than 32 slave devices
0x0101	Recoverable	GuardLink-CH[0] Tap 1 communication error	No, or corrupted, communication
0x0102	Recoverable	GuardLink-CH[0] Tap 2 communication error	No, or corrupted, communication
0x0103	Recoverable	GuardLink-CH[0] Tap 3 communication error	No, or corrupted, communication
0x0104	Recoverable	GuardLink-CH[0] Tap 4 communication error	No, or corrupted, communication
0x0105	Recoverable	GuardLink-CH[0] Tap 5 communication error	No, or corrupted, communication
0x0106	Recoverable	GuardLink-CH[0] Tap 6 communication error	No, or corrupted, communication

Table 17 - DG Safety Relay Fault Codes

Fault Codes	Туре	Name	Description
0x0107	Recoverable	GuardLink-CH[0] Tap 7 communication error	No, or corrupted, communication
0x0108	Recoverable	GuardLink-CH[0] Tap 8 communication error	No, or corrupted, communication
0x0109	Recoverable	GuardLink-CH[0] Tap 9 communication error	No, or corrupted, communication
0x010A	Recoverable	GuardLink-CH[0] Tap 10 communication error	No, or corrupted, communication
0x010B	Recoverable	GuardLink-CH[0] Tap 11 communication error	No, or corrupted, communication
0x010C	Recoverable	GuardLink-CH[0] Tap 12 communication error	No, or corrupted, communication
0x010D	Recoverable	GuardLink-CH[0] Tap 13 communication error	No, or corrupted, communication
0x010E	Recoverable	GuardLink-CH[0] Tap 14 communication error	No, or corrupted, communication
0x010F	Recoverable	GuardLink-CH[0] Tap 15 communication error	No, or corrupted, communication
0x0110	Recoverable	GuardLink-CH[0] Tap 16 communication error	No, or corrupted, communication
0x0111	Recoverable	GuardLink-CH[0] Tap 17 communication error	No, or corrupted, communication
0x0112	Recoverable	GuardLink-CH[0] Tap 18 communication error	No, or corrupted, communication
0x0113	Recoverable	GuardLink-CH[0] Tap 19 communication error	No, or corrupted, communication
0x0114	Recoverable	GuardLink-CH[0] Tap 20 communication error	No, or corrupted, communication
0x0115	Recoverable	GuardLink-CH[0] Tap 21 communication error	No, or corrupted, communication
0x0116	Recoverable	GuardLink-CH[0] Tap 22 communication error	No, or corrupted, communication
0x0117	Recoverable	GuardLink-CH[0] Tap 23 communication error	No, or corrupted, communication
0x0118	Recoverable	GuardLink-CH[0] Tap 24 communication error	No, or corrupted, communication
0x0119	Recoverable	GuardLink-CH[0] Tap 25 communication error	No, or corrupted, communication
0x011A	Recoverable	GuardLink-CH[0] Tap 26 communication error	No, or corrupted, communication
0x011B	Recoverable	GuardLink-CH[0] Tap 27 communication error	No, or corrupted, communication
0x011C	Recoverable	GuardLink-CH[0] Tap 28 communication error	No, or corrupted, communication
0x011D	Recoverable	GuardLink-CH[0] Tap 29 communication error	No, or corrupted, communication
0x011E	Recoverable	GuardLink-CH[0] Tap 30 communication error	No, or corrupted, communication
0x011F	Recoverable	GuardLink-CH[0] Tap 31 communication error	No, or corrupted, communication
0x0120	Recoverable	GuardLink-CH[0] Tap 32 communication error	No, or corrupted, communication
0x0101	Recoverable	GuardLink-CH[1] Tap 1 communication error	No, or corrupted, communication
0x0102	Recoverable	GuardLink-CH[1] Tap 2 communication error	No, or corrupted, communication
0x0103	Recoverable	GuardLink-CH[1] Tap 3 communication error	No, or corrupted, communication
0x0104	Recoverable	GuardLink-CH[1] Tap 4 communication error	No, or corrupted, communication
0x0105	Recoverable	GuardLink-CH[1] Tap 5 communication error	No, or corrupted, communication
0x0106	Recoverable	GuardLink-CH[1] Tap 6 communication error	No, or corrupted, communication
0x0107	Recoverable	GuardLink-CH[1] Tap 7 communication error	No, or corrupted, communication
0x0108	Recoverable	GuardLink-CH[1] Tap 8 communication error	No, or corrupted, communication
0x0109	Recoverable	GuardLink-CH[1] Tap 9 communication error	No, or corrupted, communication
0x010A	Recoverable	GuardLink-CH[1] Tap 10 communication error	No, or corrupted, communication
0x010B	Recoverable	GuardLink-CH[1] Tap 11 communication error	No, or corrupted, communication
0x010C	Recoverable	GuardLink-CH[1] Tap 12 communication error	No, or corrupted, communication
0x010D	Recoverable	GuardLink-CH[1] Tap 13 communication error	No, or corrupted, communication
0x010E	Recoverable	GuardLink-CH[1] Tap 14 communication error	No, or corrupted, communication
0x010F	Recoverable	GuardLink-CH[1] Tap 15 communication error	No, or corrupted, communication
0x0110	Recoverable	GuardLink-CH[1] Tap 16 communication error	No, or corrupted, communication
0x0111	Recoverable	GuardLink-CH[1] Tap 17 communication error	No, or corrupted, communication
0x0112	Recoverable	GuardLink-CH[1] Tap 18 communication error	No, or corrupted, communication
0x0113	Recoverable	GuardLink-CH[1] Tap 19 communication error	No, or corrupted, communication
Table 17 - DG Safety Relay Fault Codes

Fault Codes	Туре	Name	Description
0x0114	Recoverable	GuardLink-CH[1] Tap 20 communication error	No, or corrupted, communication
0x0115	Recoverable	GuardLink-CH[1] Tap 21 communication error	No, or corrupted, communication
0x0116	Recoverable	GuardLink-CH[1] Tap 22 communication error	No, or corrupted, communication
0x0117	Recoverable	GuardLink-CH[1] Tap 23 communication error	No, or corrupted, communication
0x0118	Recoverable	GuardLink-CH[1] Tap 24 communication error	No, or corrupted, communication
0x0119	Recoverable	GuardLink-CH[1] Tap 25 communication error	No, or corrupted, communication
0x011A	Recoverable	GuardLink-CH[1] Tap 26 communication error	No, or corrupted, communication
0x011B	Recoverable	GuardLink-CH[1] Tap 27 communication error	No, or corrupted, communication
0x011C	Recoverable	GuardLink-CH[1] Tap 28 communication error	No, or corrupted, communication
0x011D	Recoverable	GuardLink-CH[1] Tap 29 communication error	No, or corrupted, communication
0x011E	Recoverable	GuardLink-CH[1] Tap 30 communication error	No, or corrupted, communication
0x011F	Recoverable	GuardLink-CH[1] Tap 31 communication error	No, or corrupted, communication
0x0120	Recoverable	GuardLink-CH[1] Tap 32 communication error	No, or corrupted, communication
0x0200	Non-recoverable	DG safety relay is not configured	No configuration on DG safety relay
0x0201	Non-recoverable	DG safety relay configuration needs FW update	DG safety relay configuration needs FW update
0x0210	Non-recoverable	Rotary switch mismatch 00	At startup, rotary switch mismatch position must be 0
0x0211	Non-recoverable	Rotary switch mismatch 01	At startup, rotary switch mismatch position must be 1
0x0212	Non-recoverable	Rotary switch mismatch 02	At startup, rotary switch mismatch position must be 2
0x0213	Non-recoverable	Rotary switch mismatch 03	At startup, rotary switch mismatch position must be 3
0x0214	Non-recoverable	Rotary switch mismatch 04	At startup, rotary switch mismatch position must be 4
0x0215	Non-recoverable	Rotary switch mismatch 05	At startup, rotary switch mismatch position must be 5
0x0216	Non-recoverable	Rotary switch mismatch 06	At startup, rotary switch mismatch position must be 6
0x0217	Non-recoverable	Rotary switch mismatch 07	At startup, rotary switch mismatch position must be 7
0x0218	Non-recoverable	Rotary switch mismatch 08	At startup, rotary switch mismatch position must be 8
0x0219	Non-recoverable	Rotary switch mismatch 09	At startup, rotary switch mismatch position must be 9
0x021A	Non-recoverable	Rotary switch mismatch 10	At startup, rotary switch mismatch position must be 10
0x021B	Non-recoverable	Rotary switch mismatch 11	At startup, rotary switch mismatch position must be 11
0x021C	Non-recoverable	Rotary switch mismatch 12	At startup, rotary switch mismatch position must be 12
0x021D	Non-recoverable	Rotary switch mismatch 13	At startup, rotary switch mismatch position must be 13
0x021E	Non-recoverable	Rotary switch mismatch 14	At startup, rotary switch mismatch position must be 14
0x021F	Non-recoverable	Rotary switch mismatch 15	At startup, rotary switch mismatch position must be 15

<u>Table 18</u> lists the fault codes for the taps.

Table 18 - Tap Fault Codes

Fault Code Decimal (Hex)	Name	Description	Recommended Action
00 (00)	No fault	—	—
01 (01)	Channel A fault	Short circuit is detected on Channel A of the monitored field device	Check wiring Functionally test the monitored device
02 (02)	Channel B fault	Short circuit is detected on Channel B of the monitored field device	Check wiring Functionally test the monitored device
05 (05)	Power error	Power error	Evaluate supply voltage
06 (06)	Memory fault	Internal memory fault	Power cycle the unit If error persists, replace unit
07 (07)	Auto-detect fault	Failure to detect monitored field device type	Check wiring Power cycle the device
08 (08)	ROM fault	Internal memory fault	Power cycle the unit If error persists, replace unit
09 (09)	RAM fault	Runtime memory fault.	Power cycle the unit If error persists, replace unit
10 (OA)	CPU fault	Internal memory fault	Power cycle the unit If error persists, replace unit
11 (OB)	Test fault	Internal test fault	Power cycle the unit If error persists, replace unit
12 (OC)	Voltage fault	Power error	Power cycle the unit If error persists, replace unit
13 (OD)	OSSD fault	Channel A and Channel B cross fault	Check wiring Functionally test the monitored device
14 (OE)	Integrity fault	Internal memory fault	Power cycle the unit If error persists, replace unit
15 (OF)	Safety signal shutdown	No response on GuardLink	Check that the installation meets specification

<u>Table 19</u> lists the diagnostic codes for the taps.

Table 19 - Tap Diagnostic Codes

Diagnostic Code Decimal (Hex)	Name	Description
00 (00)	No diagnostic	—
01 (01)	Safety signal timeout	Safety signal timeout, check status of downstream device
02 (02)	Safety signal invalid	Safety signal invalid
03 (03)	Reset input is held on	Reset input is held on
04 (04)	Power low warning	Power out of specification
64 (40)	Device startup func. Test	Perform a functional test of the device (cycle between safe and active state)
65 (41)	Device fault, func. test	Perform a functional test of the device (cycle between safe and active state)

I/O Faulted

The following figures show how to remedy the I/O Faulted status on the EtherNet/IP interface.

An exclamation mark in a small yellow triangle indicates a fault on the EtherNet/IP interface in the Controller Organizer panel.

Figure 56 - I/O Faulted Identified

Controller Organizer		🗕 🕂 🗙		
🖃 🔄 Controller AFGL				
- 🖉 Controller T	ags			
- Controller F	ault Handler			
- Power-Up H	andler			
🖻 📇 Tasks				
🖻 🔕 Main Task				
🖃 🚭 MainPro	gram			
- 🖉 Para	ameters and Local Tags			
🔂 Mair	Routine			
- Cinscheduled	1			
🖻 🔠 Motion Groups				
- Ungrouped a	Axes			
- Call Add-On Instruct	tions			
🖻 🔠 Data Types				
- 🕞 User-Define	d			
- 🤤 Strings				
- 🛺 Add-On-Def	ined			
😥 🕼 Predefined				
🗄 🕼 Module-Defi	ned			
🗀 Trends				
🖻 😽 I/O Configuration				
🖻 📆 1769 Bus	🖃 🗐 1769 Bus			
- 🚺 [0] 1769	P-L24ER-QB1B AFGL			
🖃 🛅 Embedd	ed I/O			
L [1] E	Embedded Discrete_IO			
🛁 Expansi	on I/O			
E Ethernet				
- 🕕 1769-L2	HER-QB1B AFGL			
140R-E	NETR/B ENETR			
Module Defined	Terre			
	Trago			
Description				
Status	IO Faulted			
Module Fault	(Code 16#0009) Module Configuration Rejected: Parameter Error Additional Fault Code 16#	0000		

With an EtherNet/IP connection, do the following:

- 1. Go offline.
- 2. Click the change button.

Figure 57 - Go Offline and Change



3. Click Upload to upload the configuration that is in the EtherNet/IP interface into the project.

Figure 58 - Upload

Module Definition			X
Upload	GuardMaster		
E 440R-ENETR	Series:	в	
as reay bus	Revision:	2 💌 001 📩	
	Electronic Keying:	Compatible Module	-
	Connection:	Data-GuardLink	•
1			
	0	K Cancel Hel	P

Next, you must select the upload path.

- 4. Expand your Ethernet connection.
- 5. Select your Ethernet interface.
- 6. Click OK. The upload begins immediately.

Figure 59 - Upload Path Selection



7. Click OK when upload is complete.

Figure 60 - Upload Complete

Module Definition		×
Upload	GuardMaster	
 ☐ 440R-ENETR ➡ Relay Bus 	Series:	в
	Revision:	2 🔍 001 📩
	Electronic Keying:	Compatible Module
	Hoload 4400 Ethernet Interface	xI V
	Upload Complete	
	Uploaded configuration from 440R-8 AB_ETHIP-1\192.168.1.111.	ENETR at WIN7-VMI
		ОК
1		
	0	K Cancel Help

- 8. Click Yes to confirm the change.
- 9. Click OK.

Figure 61 - Confirm Change to Module Definition

Upload	Fielsy Bus
Lagix Designer These changes will cause mod Deax will be set to default valiver Verify module properties befor Change module definition?	Viel data types and properties to change. use unless it can be recovered from the existing module properties. re Applying changes.
8	9
	OK Cancel Help

- 10. Go online to Run mode.
- 11. Download the new configuration to the controller.

Figure 62 - Run and Download



The process is complete. The EtherNet/IP interface no longer shows an I/O Fault.

Studio 5000 Code Examples

The following are examples of code that you encounter in the Studio 5000 environment.

Lock and Unlock Commands

Figure 63 shows sample code to lock and unlock guard locking switches. Rung 9 uses an HMI input to unlock all switches in the GuardLink circuit. First, we move a zero into the LockCmd to clear out any previous lock commands. Then, we move a -1 into the UnlockCmd. The -1 is converted to a 1 for each tap. If a tap is not a guard locking switch, then the command is ignored.

Rung 10 uses an HMI input to lock all switches in the GuardLink circuit. First, we move a zero into the UnlockCmd to clear out any previous unlock commands. Then, we move a -1 into the LockCommand. The -1 is converted to a 1 for each tap. If a tap is not a guard locking switch, then the command is ignored.

Rungs 11 and 12 provide an example of unlocking and locking a specific switch. In this case, we move a 4, which is the third tap, instead of a -1.



Figure 63 - Lock and Unlock Commands

GuardLink Fault Reset Commands

Figure 64 shows sample code to reset devices on the GuardLink circuit. Rung 16 uses an HMI input to reset all devices in the GuardLink circuit. First, we move a zero into the FaultResetCmd to clear out any previous commands. Then, we move a -1 into the FaultResetCmd. The -1 is converted to a 1 for each tap. The reset is equivalent to cycling the power to each tap and device.

Rung 17 uses an HMI input to reset one tap and device. First, we move a zero into the FaultResetCmd to clear out any previous commands. Then, we move a four into the FaultResetCmd to reset the third tap and device.

Figure 64 - GuardLink Fault Reset Commands



440R-ENETR Interface Web Page

The 440R-ENETR network interface has its own built-in web page. To access the home page, type the IP address (for example, 192.168.1.210) into the URL field of any web browser. The web page has several tabs. This user manual only addresses the tabs that are associated with the DG safety relay. See publication 440R-UM009 for details on the other tabs.

Home Tab

Figure 65 shows the home page of the 440R-ENETR Series B interface. The Home tab shows the basic information of the 440R-ENETR interface, the status of the GSR relays located next the 440R-ENETR interface, the software versions of the 440R-ENETR interface, and the configuration switch setting.

Figure 65 - 440R-ENETR Series B Home Page

EROCKWELL 440R-ENETR Series E	3 - Internet Explorer		
	210/	🔎 🛃 🏉 Rockwell 440R-ENETR Series B 🗙	6 🛧 🌣
File Edit View Favorites To	ols Help		
👍 🕬 Cat 🧮 DL 🎂 AB 🗋 KB	Software	🏠 • 🔊 - 🖃 (🖶 🔹 Page 🔹 Safety 🔹 Tools 👻 🕢 👻
Allen-Bradley 44	10R-ENETR Seri	es B	Rockwell Automation
Expand Minimize	Home		
Browse GSR devices	440R-ENETR Series B		
Diagnostics	Revision	2.1	
Diagnostic Overview	Device IP address	192.168.1.210	
Network Settings	Ethernet address (MAC)	00:05:94:00:52:81	
Ethernet Statistics	Serial number	000C8781	
🚰 Administrative Settings	Uptime	0 days, 0h:1m:18s	
Network Configuration			
E-mail Configuration	Status		
	GSR connection status	OK (6 GSRs running)	Resources
	GSR faults	OK (no faults reported)	Visit <u>ab.com</u> for additional
	Rotary switch status	OK (210)	information
	Interface connection status	No class 1 connection open.	
	Software versions		
	EtherNet/IP FW revision	1.35.1-0	
	Controller FW revision	2.1.0-129	
	Web pages revision	2.1.0-1	
	Configuration		
	Switch setting (startup/current)	210/210	
	3	Seconds Between Refresh: 0 Disable Refresh with 0.	
	Copyright © 2016 Rockwell Automat	ion, Inc. All Rights Reserved.	

Browse GSR Devices Tab

Figure 66 on page 81 shows the Browse GSR Devices tab. The top of the page gives an overview. In this example, one older GSR relay is communicating on optical bus 2, and five DG safety relays are communicating on optical bus3.

The Device ID for the DG safety relay is 10. The safety relay has firmware revision 1.5 and is running with no faults.

The DG Input Data shows that SafetyInput01 (IN1) is ON and SafetyInput02 (IN2) is OFF. With PtS12 true, the GuardLink circuit is active. PtX2 is true, which means OUT X (terminal X2) is ON. With Pt13_14 and Pt23_24 true, terminals 13/14 and 23/24 are ON. The Config has a value of 0x2 (each configuration has a unique number). The time delay switch has a value of 0xc, which is position 12. The DG safety relay has no faults.

The DG Output Data shows the status of the reset.

The GuardLink1 - Input Data fields show that GuardLink is used for IN1 and is not tripped. When not tripped, the DeviceTrip (0xf) equals the DeviceCount (0xf).

The GuardLink1 – Output Data fields show status of the Lock, Unlock, and Fault Reset commands.

Similar fields exist for GuardLink2 Input and Output.

The status of the other relays that the 440R-ENETR interface monitors can be viewed by scrolling down the web page.

UnlockCmd

LockCmd FaultResetCmd 0x0 0x0

0x0

Figure 66 - Browse GSR Devices Tab

🄁 🕘 🗢 🎑 http://192.168.1						
	210/ 🔎	💽 🐓 🙆 Rockv	vell 440R-ENETR Serie	es B 🗙		
Allen-Bradley		uian D	Ro	ckwell		
Anen-brauley 4	40R-ENETR Se	ries B	Autor	nation		
Expand Minimize	Browse GSR devices					
Bulance	browse don devices					
Home				-		
Browse GSR devices	Overview					
Diagnostics	Port type/series	OLink v2	OLink v3			
Diagnostic Overview	Bus running	Bus running OK	Bus running OK	:		
Network Settings	Number of devices found on bus	1	5			
Ethernet Statistics	Error counters:					
Administrative Settings	UART framing/parity error:	0	0			
	UART or receive buffer overrun:	0	ō			
Network Configuration	receive timeout error:	0	0			
E-mail Configuration	CRC error:	0	0			
	unexpected/wrong data	õ	õ			
	Teceived:					
	GSR device #1		_		 	
	Device Id 10				440R-D	G2R2T - DG Output I
	Firmware version 1.5	5			Reset1	false
	Running tru	e			FaultReset	false
	Major Fault Descriptor 0.0)			Gua	edLink1 - Input Data
	Minor Fault Descriptor 0x	0				
	440R-DG2R2T - DG	Input Data			Active	true
	C-(Trip	false
	SafetyInput01 tru	ie			DiagnosticActive	talse
	SafetyInput02 fail	se			Fault	faise
	PtS12 tru	le			DiagnosticCode	UXU
	PtS22 fai	se			FaultCode	0x0
	PtS32 fall	se			DeviceTrip	Oxt
	Pt542 fai	se			DeviceDiagnostic	UXU QuQ
	PtS11 fai	se			DeviceFault	0x0
	Pt521 fai	se 			DeviceCount	Uxr
	PtX1 fai	se			Guar	dLink1 - Output Dat
	PDA2 tru				UnlockCmd	0x0
	PLAS Tal	se			LockCmd	0x0
	Pt/4 14	se 			FaultResetCmd	0x0
	Pt13_14 tru				Cua	edLink2 - Input Data
	ResetRequired1 fall				Guu	inclinki input but
	ResetHeldOn1 fail	56			Active	false
	NonRecoverableFault fail	50			Trip	false
	Fault fal	50			DiagnosticActive	false
	FaultCode 0vi	0			Fault	false
	Config 0v	2			DiagnosticCode	0x0
	ValueBotarySwitch 0x	-			FaultCode	0x0
	Caracterization (CAR	-			DeviceTrip	0x0
					DeviceDiagnostic	0x0
					DeviceDiagnostic DeviceFault	0x0 0x0

Notes:

Specifications

DG Safety Relay

Table 20 - General Specifications — DG Safety Relay

Attribute	440R-DG2R2T
Dimensions, H x W x D	119.14 x 22.5 x 113.6 mm (6.49 x 0.88 x 4.47 in.)
Shipping weight, approx.	225 g (0.5 lb)
Wire size	0.22.5 mm ² (2414 AWG)
Wiring category	Copper that withstands 75 °C (167 °F)
Insulation stripping length	7 mm (0.28 in.)
Terminal screw torque	0.4 N•m (4 lb•in)
Power supply voltage range	24V DC PELV/SELV, UL Class 1 Div. 2., 0.851.1 x rated voltage
Power consumption	3.5 W
Power on delay	5.5 s
Case material	Polyamide PA 6.6
Terminal protection	IP20
Enclosure protection	IP40 (NEMA 1)
Mounting	35 mm (1.4 in.) DIN rail in enclosure that is rated to a minimum of IP54

Table 21 - Environmental Specifications — DG Safety Relay

Attribute	440R-DG2R2T
Temperature, operating	-5+55 °C (23131 °F)
Relative humidity	90%
Vibration	1055 Hz, 0.35 mm
Shock	10 g, 16 ms
Pollution level	2
Installation group	Overvoltage Category III, VDE 0110-1
Impulse withstand voltage	2500V

Attribute	440R-DG2R2T
Wiring terminals	S11/S21
Continuous output current, max	100 mA
Surge output current, max	0.7 A
Surge output current duration, max	5 ms
Residual voltage drop from P/S, max	0.6V
Load capacitance, max [nF/mA load]	200/20 100/10 22/0
Off state leakage current, max	< 0.1 mA
Short circuit detection	Yes
Short circuit protection	Yes
Galvanic isolation: I/O from logic	No
Pulse test duration	≤700 µs
Pulse test period	5 ms

Table 22 - Pulse Test Output Specifications — DG Safety Relay

Table 23 - Inj	out Devices with Vol	tage-free Contacts S	Specifications —	DG Safety	/ Relay

Attribute	440R-DG2R2T
Wiring terminals	S12/S22 and S32/S42
ON voltage, max	26.4V
ON voltage, min	11V
OFF voltage, max	5V
OFF current, max	2 mA
ON current, min at 20V DC	10 mA
Galvanic isolation: I/O from logic	No
Off pulse that is accepted for OSSD setting without declaring the input as OFF	$ \begin{aligned} \text{Min} &= 0 \ \mu \text{s} \\ \text{Max} &= 700 \ \mu \text{s} \end{aligned} $
Off pulse period, min	15 ms
Input capacitance	220 nF

Attribute	440R-DG2R2T
Wiring terminal	Output - X2 Input - X1
Continuous output current, max	50 mA
ON state voltage drop (P/S to +), max	0.2V
Surge output current, max	700 mA
Surge output current duration, max	5 ms
Load capacitance, max	1μF
Off state leakage current, max	< 0.1 mA
Short circuit detection	No
Short circuit protection	Yes
Galvanic isolation: I/O from logic	No
Fan-out (Max number of connections to L11)	10
Cable length between L11 and L12	30 m (98.4 ft)
Off state leakage current, max	< 0.1 mA
Short circuit detection	Yes
Short circuit protection	Yes

Table 24 - SWS Specifications — DG Safety Relay

Table 25 - Safety Output Specifications — DG Safety Relay

Attribute	440R-DG2R2T			
Wiring terminals	13/14, 23/24			
Types	2 N.O.			
Thermic current I _{th}	1x6A			
Fuses output (external)	6 A slow blow or 10 A quick blow			
Switched current, min	10 mA			
Switched voltage, min	10V			
Mechanical life	10,000,000 cycles			
Rating	UL:C300 AC-15:1.5 A / 250V AC DC13: 2 A / 24V DC (0.1 Hz)			
Contact material	AgNi + 0.2 μ Au			
Reaction times				
Automatic reset	<100 ms			
Monitored manual reset	<500 ms			
Response time				
13/14 and 23/24 safety outputs	35 ms			
SWS output	30 ms			
Recovery time	100 ms			

Тар

Table 26 - General Specifications — Tap

Attribute	440S-SF8D, 440S-SF5D, 440S-MF5D, 440S-MF8D
Dimensions, L x W x H	79.64 x 38.5 x 17 mm (3.14 x 1.51 x 0.67 in.)
Shipping weight, approx.	27.2 g (0.96 oz)
Case material	Red RAL 3020 unfilled ABS MG47C plastic
Mounting screw torque	2.25 N•m (20 lb•in)
Mounting	Any orientation

Table 27 - Electrical Specifications — Tap

Attribute	440S-SF8D, 440S-SF5D, 440S-MF5D, 440S-MF8D			
Voltage requirements	24V DC +10%, -15%			
Supply over voltage protection, Max	60V DC			
Reverse polarity protection	Yes			
Short circuit protection				
OSSD supply and lock signal	700 mA			
GuardLink [™] signals	500 mA			
ON voltage, max	26.4V			
ON voltage, min	11V			
OFF voltage, max	5V			
OFF current, max	2 mA			
ON current, min at 20V DC	10 mA			
Galvanic isolation: I/O from logic	No			
Off pulse that is accepted for OSSD setting without declaring the input as OFF	Min = 0 μs Max = 700 μs			
Off pulse period, min	15 ms			
Input capacitance	220 nF			
Current consumption				
EMSS input ON	40 mA			
EMSS input OFF	25 mA			
OSSD input ON	29 mA			
OSSD input OFF	25 mA			
Voltage that is supplied to OSSD device co	nnected to the J3 connector			
Pin1 of 5-pin OSSD	J1 supply voltage -1.2V @ 500 mA, max load, 0.4V at 50 mA load			
Pin 2 of 8-pin OSSD	J1 supply voltage -1.2V @ 500 mA, max load, 0.4V at 50 mA load			
Response Time				
EMSS SmartTap	5 mc plus 25 us far and unstrant tap			
OSSD SmartTap	s ms pius so μs for each upstream tap			
CLU timing between successive lock/ unlock	135300 ms			

Attribute	Tap: 440S-SF8D, 440S-SF5D, 440S-MF5D, 440S-MF8D Terminator: 898D-418U-DM2
Temperature	•
Operating	-25+70 °C (-13+158 °F)
Storage	-40+85 °C (-40+185 °F)
Relative humidity	3585%, not exceed 50%RH at 70 °C (158 °F)
Vibration per IEC 60068-2-6	1055 Hz, 1 mm
Shock per IEC 60068-2-27	30 g, 11 ms, half-sine
Pollution level per IEC 60947-5-2	3
Enclosure protection	IP65, IP67 washdown according to EN 60529, UL Type 1 PR61413
Flammability	UL94, DIN 752000/FMV 55302
Protection against electric shock	Class III per EN 61140
Emissions	CISPR 11

Table 28 - Environmental Specifications — Tap and Terminator

Notes:

Configuration Examples

This appendix contains examples of configurations. Each example contains the following:

• Schematic

This diagram shows the major connections. The input devices are not shown because of multiple configuration options.

• Logic diagram

This diagram shows the safety monitoring function (SMF), the logic level, and the safety output function (SOF).

• Configuration table

This table shows potential examples of configuration for the corresponding schematic and logic diagram. Each configuration also shows the color of the status indicators during configuration. If in Run mode, a short press of the Config/Set button also shows these indicators.

In Configuration 1, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink[™] or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is configured for SWS In; this input is ANDed with IN 1 and IN 2.

The output OUT X (terminal X2) is configured for SWS Out and can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. OUT X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The relay configuration is considered a middle SWS as it requires an SWS input and provides an SWS output.

The Reset mode is configured for manual monitored reset and is assigned to the safety outputs. The outputs are enabled when all inputs of the safety function are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

Figure 67 - Two Safety Inputs, Middle SWS, and Monitored Manual Reset Assigned to Safety Outputs Schematic





Table 29 - Configuration 1

Indicator	Function	Configuration ID: 0x7F		Configuration ID: 0x7B		Configuration ID: 0x7D		Configuration ID: 0x79	
OUT	Safety Functions		IN1 and IN2						
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS
OUT X	Output Type		SWS		SWS		SWS		SWS
IN X	Input Mode		SWS Enabled		SWS Enabled		SWS Enabled		SWS Enabled
Reset	Reset Type		Monitored Manual		Monitored Manual		Monitored Manual		Monitored Manual
FB	Reset Assignment		SOF		SOF		SOF		SOF

In Configuration 2, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is configured for SWS In. This input is ANDed with IN 1 and IN 2.

The output OUT X (terminal X2) is configured for SWS Out and can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. OUT X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The relay configuration is considered a middle SWS as it requires an SWS input and provides an SWS output.

The Reset mode is configured for manual monitored reset that is assigned to Input 1. After a demand of the safety function by Input 1, the outputs are enabled when all safety inputs are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

After a demand of the safety function by Input 2 or IN X, the outputs are enabled when the IN 2 and IN X safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.



Figure 68 - Two Safety Inputs, Middle SWS, Monitored Manual Reset Assigned to Input 1, Automatic Reset Assigned to Input 2 Schematic Logic



Table 30 - Configuration 2

Indicator	Function	6	Configuration ID: 0x3F		Configuration ID: 0x3B		Configuration ID: 0x3D		Configuration ID: 0x39	
OUT	Safety Functions		IN1 and IN2		IN1 and IN2		IN1 and IN2		IN1 and IN2	
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS	
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS	
OUT X	Output Type		SWS		SWS		SWS		SWS	
IN X	Input Mode		SWS Enabled		SWS Enabled		SWS Enabled		SWS Enabled	
Reset	Reset Type		Monitored Manual		Monitored Manual		Monitored Manual		Monitored Manual	
FB	Reset Assignment		SMF IN1		SMF IN1		SMF IN1		SMF IN1	

In Configuration 3, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is configured for SWS In. This input is ANDed with IN 1 and IN 2.

The output OUT X (terminal X2) is configured for SWS Out and can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. OUT X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The relay configuration is considered a middle SWS as it requires an SWS input and provides an SWS output.

The Reset mode is configured for automatic and assigned to the safety outputs. After a demand of the safety function by any input, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.

Logic





Table 31 - Configuration 3

Indicator	Function	Configuration ID: 0x1F		Configuration ID: 0x1B		Configuration ID: 0x1D		Configuration ID: 0x19		
OUT	Safety Functions		IN1 and IN2							
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS	
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS	
OUT X	Output Type		SWS		SWS		SWS		SWS	
IN X	Input Mode		SWS Enabled		SWS Enabled		SWS Enabled		SWS Enabled	
Reset	Reset Type		Automatic		Automatic		Automatic		Automatic	
FB	Reset Assignment		Not used		Not used		Not used		Not used	

In Configuration 4, only safety Input 1 is in use. It can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is configured for SWS In. This input is ANDed with IN 1.

The output OUT X (terminal X2) is configured for SWS Out and can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. OUT X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The relay configuration is considered a middle SWS as it requires an SWS input and provides an SWS output.

The Reset mode is configured for manual monitored reset and is assigned to the safety outputs. The outputs are enabled when all inputs of the safety function are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.







		i			
Indicator	Function	Co	onfiguration ID: 0x7A	Co	onfiguration ID: 0x78
OUT	Safety Functions		IN1		IN1
IN 1	Input Type		GuardLink		OSSD/EMSS
IN 2	Input Type		Not used		Not used
OUT X	Output Type		SWS		SWS
IN X	Input Mode		SWS Enabled		SWS Enabled
Reset	Reset Type		Monitored Manual		Monitored Manual
FB	Reset Assignment		SOF		SOF

In Configuration 5, only safety Input 1 is in use. It can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is configured for SWS In. This input is ANDed with IN 1.

The output OUT X (terminal X2) is configured for SWS Out and can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. OUT X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The relay configuration is considered a middle SWS as it requires an SWS input and provides an SWS output.

The Reset mode is configured for automatic/manual and assigned to the safety outputs. After a demand of the safety function by any input, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.

Logic







Indicator	Function	Co	onfiguration ID: 0x1A	Co	onfiguration ID: 0x18
OUT	Safety Functions		IN1		IN1
IN 1	Input Type		GuardLink		OSSD/EMSS
IN 2	Input Type		Not used		Not used
OUT X	Output Type		SWS		SWS
IN X	Input Mode		SWS Enabled		SWS Enabled
Reset	Reset Type		Automatic		Automatic
FB	Reset Assignment		Not used		Not used

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In Configuration 6, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN 1 (terminal X1) is disabled; there is no connection to terminal X1.

The output OUT X (terminal X2) is configured for SWS Out. SWS Out can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. OUT X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The relay configuration is considered a first SWS as it does not require SWS input and provides an SWS output.

The Reset mode is configured for manual monitored reset and is assigned to the safety outputs. The outputs are enabled when all safety inputs are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.





Table 34 - Configuration 6

Indicator	Function	6	onfiguration ID: 0x6F	C	onfiguration ID: 0x6B	Configuration ID: 0x6D		6	onfiguration ID: 0x69
OUT	Safety Functions		IN1 and IN2		IN1 and IN2		IN1 and IN2		IN1 and IN2
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS
OUT X	Output Type		SWS		SWS		SWS		SWS
IN X	Input Mode		Disabled		Disabled		Disabled		Disabled
Reset	Reset Type		Monitored Manual		Monitored Manual		Monitored Manual		Monitored Manual
FB	Reset Assignment		SOF		SOF		SOF		SOF

In Configuration 7, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN 1 (terminal X1) is disabled; there is no connection to terminal X1.

The output Out X (terminal X2) is configured for SWS Out. SWS Out can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. Output Out X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The Reset mode is configured for manual monitored reset and is assigned to Input 1. After a demand of the safety function by Input 1, the outputs are enabled when all safety inputs are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

After a demand of the safety function by Input 2, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.







Table 35 - Configuration 7

Indicator	Function	Co	nfiguration ID: 0x2F	Co	onfiguration ID: 0x2B	Co	onfiguration ID: 0x2D	6	onfiguration ID: 0x29
OUT	Safety Functions		IN1 and IN2		IN1 and IN2		IN1 and IN2		IN1 and IN2
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS
OUT X	Output Type		SWS		SWS		SWS		SWS
IN X	Input Mode		Disabled		Disabled		Disabled		Disabled
Reset	Reset Type		Monitored Manual		Monitored Manual		Monitored Manual		Monitored Manual
FB	Reset Assignment		SMF IN1		SMF IN1		SMF IN1		SMF IN1

In Configuration 8, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN 1 (terminal X1) is disabled; there is no connection to terminal X1.

The output Out X (terminal X2) is configured for SWS Out. SWS Out can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. Output Out X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The relay configuration is considered a first SWS as it does not require SWS input and provides an SWS output.

The Reset mode is configured for automatic manual and assigned to the safety outputs. After a demand of the safety function by any input, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.





Table 36 - Configuration 8

Indicator	Function	Co	onfiguration ID: 0x0F	Co	onfiguration ID: 0x0B	Co	onfiguration ID: 0x0D	6	onfiguration ID: 0x09
OUT	Safety Functions		IN1 and IN2		IN1 and IN2		IN1 and IN2		IN1 and IN2
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS
OUT X	Output Type		SWS		SWS		SWS		SWS
IN X	Input Mode		SWS Enabled		SWS Enabled		SWS Enabled		SWS Enabled
Reset	Reset Type		Automatic		Automatic		Automatic		Automatic
FB	Reset Assignment		Not used		Not used		Not used		Not used

In Configuration 9, only safety Input 1 is in use. It can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN 1 (terminal X1) is disabled; there is no connection to terminal X1.

The output Out X (terminal X2) is configured for SWS Out. SWS Out can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. Output Out X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The relay configuration is considered a first SWS as it does not require SWS input and provides an SWS output.

The Reset mode is configured for manual monitored reset and is assigned to the safety outputs. The outputs are enabled when all inputs of the safety function are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

IN 1

&

R

FB

OUT 14/24







Indicator	Function	Co	onfiguration ID: 0x6A	Co	onfiguration ID: 0x68
OUT	Safety Functions		IN1		IN1
IN 1	Input Type		GuardLink		OSSD/EMSS
IN 2	Input Type		Not used		Not used
OUT X	Output Type		SWS		SWS
IN X	Input Mode		SWS Disabled		SWS Disabled
Reset	Reset Type		Monitored Manual		Monitored Manual
FB	Reset Assignment		SOF		SOF

In Configuration 10, only safety Input 1 is in use. It can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN 1 (terminal X1) is disabled; there is no connection to terminal X1.

The output Out X (terminal X2) is configured for SWS Out. SWS Out can drive any other SWS compatible device. In this example, the SWS out is driving an EM safety relay. Output Out X is switched off immediately when demanded by the safety functions. The relay outputs 14/24 can be configured for a time delay to switch off after the delay time.

The relay configuration is considered a first SWS as it does not require SWS input and provides an SWS output.

The Reset mode is configured for automatic and assigned to the safety outputs. After a demand of the safety function by any input, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.









Indicator	Function	Co	onfiguration ID: 0x0A	Co	onfiguration ID: 0x08
OUT	Safety Functions		IN1		IN1
IN 1	Input Type		GuardLink		OSSD/EMSS
IN 2	Input Type		Not used		Not used
OUT X	Output Type		SWS		SWS
IN X	Input Mode		SWS Disabled		SWS Disabled
Reset	Reset Type		Automatic		Automatic
FB	Reset Assignment		Not used		Not used

In Configuration 11, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The output type for OUT X (terminal X2) is configured for OSSD, and input IN X (terminal X1) is enabled. In this mode, IN X accepts a 24V DC input signal and output OUT X can be used as an immediate switching safety output to initiate a stop function of a drive. The 2-channel safety output 14/24 can drive the safety circuit for a Safe Torque Off with a delay time to perform a Stop Category 1 function.

The Reset mode is configured for manual monitored reset and is assigned to the safety outputs. The outputs are enabled when all inputs of the safety function are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

Figure 77 - Two Safety Inputs, No SWS, Monitored Manual Assigned to Safety Outputs Schematic



Table 39 - Configuration 11

Indicator	Function	Co	onfiguration ID: 0x77	Co	onfiguration ID: 0x73	Co	onfiguration ID: 0x75	6	onfiguration ID: 0x71
OUT	Safety Functions		IN1 and IN2		IN1 and IN2		IN1 and IN2		IN1 and IN2
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS
OUT X	Output Type		OSSD		OSSD		OSSD		OSSD
IN X	Input Mode		OSSD Enabled		OSSD Enabled		OSSD Enabled		OSSD Enabled
Reset	Reset Type		Monitored Manual		Monitored Manual		Monitored Manual		Monitored Manual
FB	Reset Assignment		SOF		SOF		SOF		SOF

In Configuration 12, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The output type for OUT X (terminal X2) is configured for OSSD, and input IN X (terminal X1) is enabled. In this mode, IN X accepts a 24V DC input signal and output OUT X can be used as an immediate switching safety output to initiate a stop function of a drive. The 2-channel safety output 14/24 can drive the safety circuit for a Safe Torque Off with a delay time to perform a Stop Category 1 function.

The Reset mode is configured for manual monitored reset and is assigned to Input 1. After a demand of the safety function by Input 1, the outputs are enabled when all safety inputs are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

After a demand of the safety function by Input 2, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.





Table 40 - Configuration 12

Indicator	Function	Co	onfiguration ID: 0x37	6	onfiguration ID: 0x33	Configuration ID: 0x35		6	onfiguration ID: 0x31
OUT	Safety Functions		IN1 and IN2		IN1 and IN2		IN1 and IN2		IN1 and IN2
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS
OUT X	Output Type		OSSD		OSSD		OSSD		OSSD
IN X	Input Mode		OSSD Enabled		OSSD Enabled		OSSD Enabled		OSSD Enabled
Reset	Reset Type		Monitored Manual		Monitored Manual		Monitored Manual		Monitored Manual
FB	Reset Assignment		SMF IN1		SMF IN1		SMF IN1		SMF IN1

In Configuration 13, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The output type for OUT X (terminal X2) is configured for OSSD, and input IN X (terminal X1) is enabled. In this mode, IN X accepts a 24V DC input signal and output OUT X can be used as an immediate switching safety output to initiate a stop function of a drive. The 2-channel safety output 14/24 can drive the safety circuit for a Safe Torque Off with a delay time to perform a Stop Category 1 function.

The Reset mode is configured for automatic and assigned to the safety outputs. After a demand of the safety function by any input, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.

Figure 79 - No SWS, Two Safety Inputs, Automatic Restart Assigned to Safety Outputs Schematic



Table 41 - Configuration 13

Indicator	Function	6	onfiguration ID: 0x17	6	onfiguration ID: 0x13	6	Configuration ID: 0x15		onfiguration ID: 0x11
OUT	Safety Functions		IN1 and IN2		IN1 and IN2		IN1 and IN2		IN1 and IN2
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS
OUT X	Output Type		OSSD		OSSD		OSSD		OSSD
IN X	Input Mode		OSSD Enabled		OSSD Enabled		OSSD Enabled		OSSD Enabled
Reset	Reset Type		Automatic		Automatic		Automatic		Automatic
FB	Reset Assignment		Not used		Not used		Not used		Not used

In Configuration 14, only safety Input 1 is in use. It can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The output type for OUT X (terminal X2) is configured for OSSD, and input IN X (terminal X1) is enabled. In this mode, IN X accepts a 24V DC input signal and output OUT X can be used as an immediate switching safety output to initiate a stop function of a drive. The 2-channel safety output 14/24 can drive the safety circuit for a Safe Torque Off with a delay time to perform a Stop Category 1 function.

The Reset mode is configured for manual monitored reset and is assigned to the safety outputs. The outputs are enabled when all inputs of the safety function are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

Logic

Figure 80 - No SWS, One Safety Input, Monitored Manual Reset Assigned to Safety Outputs Schematic



Table 42 - Configuration 14

Indicator	Function	Co	onfiguration ID: 0x72	Co	onfiguration ID: 0x70
OUT	Safety Functions		IN1		IN1
IN 1	Input Type		GuardLink		OSSD/EMSS
IN 2	Input Type		Not used		Not used
OUT X	Output Type		OSSD		OSSD
IN X	Input Mode		OSSD Enabled		OSSD Enabled
Reset	Reset Type		Monitored Manual		Monitored Manual
FB	Reset Assignment		SOF		SOF

In Configuration 15, only safety Input 1 is in use. It can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The output type for OUT X (terminal X2) is configured for OSSD, and input IN X (terminal X1) is enabled. In this mode, IN X accepts a 24V DC input signal and output OUT X can be used as an immediate switching safety output to initiate a stop function of a drive. The 2-channel safety output 14/24 can drive the safety circuit for a Safe Torque Off with a delay time to perform a Stop Category 1 function.

The Reset mode is configured for automatic and assigned to the safety outputs. After a demand of the safety function by any input, the outputs are enabled when the Input 1 safety input is ACTIVE and the feedback signal is present. A reset operation is not required.

Logic

Figure 81 - No SWS, One Safety Function, Automatic Reset Assigned to Safety Outputs Schematic



Table 43 - Configuration 15

Indicator	Function	Co	onfiguration ID: 0x12	Co	onfiguration ID: 0x10
OUT	Safety Functions		IN1		IN1
IN 1	Input Type		GuardLink		OSSD/EMSS
IN 2	Input Type		Not used		Not used
OUT X	Output Type		OSSD		OSSD
IN X	Input Mode		OSSD Enabled		OSSD Enabled
Reset	Reset Type		Automatic		Automatic
FB	Reset Assignment		Not used		Not used

In Configuration 16, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is disabled. The output type for OUT X (terminal X2) is configured for OSSD and can be used as a status output or to drive another control device.

The reset mode is configured for manual monitored reset and is assigned to the safety outputs. The outputs are enabled when all safety inputs are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

Logic







Table 44 - Configuration 16

Indicator	Function	Co	nfiguration ID: 0x67	Co	onfiguration ID: 0x63	Configuration ID: 0x65		6	onfiguration ID: 0x61
OUT	Safety Functions		IN1 and IN2		IN1 and IN2		IN1 and IN2		IN1 and IN2
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS
OUT X	Output Type		OSSD		OSSD		OSSD		OSSD
IN X	Input Mode		OSSD Disabled		OSSD Disabled		OSSD Disabled		OSSD Disabled
Reset	Reset Type		Monitored Manual		Monitored Manua		Monitored Manual		Monitored Manual
FB	Reset Assignment		SOF		SOF		SOF		SOF

In Configuration 17, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is disabled. The output type for OUT X (terminal X2) is configured for OSSD and can be used as a status output or to drive another control device.

The Reset mode is configured for manual monitored reset and is assigned to Input 1. After a demand of the safety function by Input 1, the outputs are enabled when all safety inputs are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

After a demand of the safety function by Input 2, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.

Figure 83 - No SWS, Two Safety Inputs, Monitored Manual Reset Assigned to Input 1, Automatic Reset Assigned to Input 2 Schematic Logic





Table 45 - Configuration 17

Indicator	Function	Configuration ID: 0x27	Configuration ID: 0x23	Configuration ID: 0x25	Configuration ID: 0x21
OUT	Safety Functions	IN1 and IN2	IN1 and IN2	IN1 and IN2	IN1 and IN2
IN 1	Input Type	GuardLink	GuardLink	OSSD/EMSS	OSSD/EMSS
IN 2	Input Type	GuardLink	OSSD/EMSS	GuardLink	OSSD/EMSS
OUT X	Output Type	OSSD	OSSD	OSSD	OSSD
IN X	Input Mode	OSSD Disabled	OSSD Disabled	OSSD Disabled	OSSD Disabled
Reset	Reset Type	Monitored Manual	Monitored Manua	Monitored Manual	Monitored Manual
FB	Reset Assignment	SMF IN1	SMF IN1	SMF IN1	SMF IN1
Configuration 18

In Configuration 18, both safety inputs, Input 1 and Input 2, are in use. They can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is disabled. The output type for OUT X (terminal X2) is configured for OSSD and can be used as a status output or to drive another control device.

The reset mode is configured for automatic and assigned to the safety outputs. After a demand of the safety function by any input, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.

Figure 84 - No SWS, Two Safety Inputs, Automatic Reset Assigned to Safety Outputs Schematic





Table 46 - Configuration 18

Indicator	Function	Co	onfiguration ID: 0x07	7 Configuration ID: 0x0		Configuration ID: 0x05		Configuration ID: 0x01	
OUT	Safety Functions		IN1 and IN2		IN1 and IN2		IN1 and IN2		IN1 and IN2
IN 1	Input Type		GuardLink		GuardLink		OSSD/EMSS		OSSD/EMSS
IN 2	Input Type		GuardLink		OSSD/EMSS		GuardLink		OSSD/EMSS
OUT X	Output Type		OSSD		OSSD		OSSD		OSSD
IN X	Input Mode		OSSD Disabled		OSSD Disabled		OSSD Disabled		OSSD Disabled
Reset	Reset Type		Automatic		Automatic		Automatic		Automatic
FB	Reset Assignment		Not used		Not used		Not used		Not used

Configuration 19

In Configuration 19, only safety Input 1 is in use. It can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is disabled. The output type for OUT X (terminal X2) is configured for OSSD and can be used as a status output or to drive another control device.

The reset mode is configured for manual monitored reset and is assigned to the safety outputs. The outputs are enabled when all inputs of the safety function are ACTIVE, the feedback signal is present, and a valid reset operation has been performed.

Figure 85 - First SWS Device, One Safety Input, Monitored Manual Reset Assigned to Safety Outputs Schematic Logic



Table 47 - Configuration 19

Indicator	Function	Co	onfiguration ID: 0x62	Configuration ID: 0x60		
OUT	Safety Functions		IN1		IN1	
IN 1	Input Type		GuardLink		OSSD/EMSS	
IN 2	Input Type		Not used		Not used	
OUT X	Output Type		OSSD		OSSD	
IN X	Input Mode		OSSD Disabled		OSSD Disabled	
Reset	Reset Type		Monitored Manual		Monitored Manual	
FB	Reset Assignment		SOF		SOF	

IN 1

&

FB

Configuration 20

In Configuration 20, only safety Input 1 is in use. It can either be configured for GuardLink or OSSD with autodetect of EMSS devices. Input devices are not shown in the drawing.

The input IN X (terminal X1) is disabled. The output type for OUT X (terminal X2) is configured for OSSD and can be used as a status output or to drive another control device.

The reset mode is configured for automatic and assigned to the safety outputs. After a demand of the safety function by any input, the outputs are enabled when all safety inputs are ACTIVE and the feedback signal is present. A reset operation is not required.

Figure 86 - No SWS, One Safety Input, Automatic Reset Assigned to Safety Outputs Schematic



Table 48 - Configuration 20

Indicator	Function	Configuration ID: 0x02		Configuration ID: 0x00		
OUT	Safety Functions		IN1		IN1	
IN 1	Input Type		GuardLink		OSSD/EMSS	
IN 2	Input Type		Not used		Not used	
OUT X	Output Type		OSSD		OSSD	
IN X	Input Mode		OSSD Enabled		OSSD Enabled	
Reset	Reset Type		Automatic		Automatic	
FB	Reset Assignment		Not used		Not used	

Notes:

Regulatory Approvals

Agency Certifications

- UL Listed Industrial Control Equipment, certified for US and Canada.
- CE Marked for all applicable directives
- RCM marked for all applicable acts
- CCC Mark
- S-Mark
- KC marked for Korea

Waste Electrical and Electronic Equipment (WEEE)

Compliance to European Union Directives

At the end of its life, this equipment should be collected separately from any unsorted municipal waste.

This product has the CE Marking and is approved for installation within the European Union and EEA regions. It has been designed and tested to meet the following directives.

- Electromagnetic compatibility EMC Directive 2014/30/EU
- Low Voltage Directive 2014/35/EU
- Machinery Directive 2006/42/EC

Machine Safety Directive

This product is designed and tested to meet the European Council Directive 2006/42/EC on machinery and the following standards.

- IEC/EN 61508 Functional safety of electrical/electronic/ programmable electronic safety-related systems
- IEC/EN 62061 Safety of machinery Functional safety of safetyrelated electrical, electronic, and programmable electronic control systems
- EN ISO 13849-1 Safety of machinery Safety-related parts of control systems Part 1: General principles for design

This product is intended for use in an industrial environment.

DG Safety Relay Ratings

SIL Rating

The DG safety relay meets the requirements of SIL in accordance with IEC/ EN 61508 and SIL CL 3 in accordance with IEC/EN 62061.

Table 49 - SIL Ratings

Attribute	440R-DG2R2T
Safety integrity level	3
Safety integrity level claim limit [SILCL]	3
PFH _d [1/h]	1.92 x 10 ⁻⁸
Mode of operation	High-demand mode
Safety-related subsystems	Type B (use of programmable / complex components)
Hardware fault tolerance	HFT = 1 (dual channel system) HFT = 0 (single channel system)
Proof test interval, max [a]	20
Safe failure fraction [%]	98.9
Diagnostic coverage [%]	97.12

Performance Level/Category

The Performance Level of the safety function is dependent on the structure of all devices that comprise the safety function.

The DG safety relay is capable of being used in safety systems meeting up to Category 4 and Performance Level PLe in accordance with ISO 13849-1.

Table 50 - DG Performance Level Ratings

Attribute	440R-DG2R2T
Category	Up to 4
Performance Level	Up to e
MTTF _d [a]	92.2
DC _{avg} [%]	97.31
SFF [%]	99.06
CCF	80

Tap Ratings

SIL Rating

The tap modules can be used in systems that require up to SIL 3 in accordance with IEC/EN 61508 and SIL CL 3 in accordance with EN 62061. A comprehensive analysis of the components that comprise the safety system function determines the actual performance rating.

Table 51 - Tap SIL Ratings

Attribute	440S-SF8D, 440S-SF5D, 440S-MF5D, 440S-MF8D
Safety integrity level	3
Safety integrity level claim limit [SILCL]	3
PFH _d [1/h]	2.65 x 10 ⁻¹⁰
Mode of operation	High-demand mode
Proof test interval, max [a]	20
Safe failure fraction [%]	98.68

Table 52 - Tap Lock Command SIL Ratings

Attribute	440S-SF8D, 440S-SF5D, 440S-MF5D, 440S-MF8D
Safety integrity level	2
Safety integrity level claim limit [SILCL]	2
PFH _d [1/h]	1.5 x 10 ⁻⁹
Mode of operation	High-demand mode
Proof test interval, max [a]	20
Safe failure fraction [%]	98.16

EMC Directive

This product is designed and tested to meet the European Council Directive 2014/30/EU on Electromagnetic Compatibility (EMC) and the following standards:

- EN 55011: Industrial, scientific, and medical equipment Radio frequency disturbance characteristics - Limits and methods of measurement CISPR 11:2009 (Modified)
- EN 61000-6-2: Generic Standards Immunity for Industrial Environments
- EN 61000-6-7: Electromagnetic compatibility (EMC) Generic standards. Immunity requirements for equipment that is intended to perform functions in a safety-related system (functional safety) in industrial locations.
- EN 61326-3-1: Electrical equipment for measurement, control, and laboratory use - EMC requirements - Part 3-1: Immunity requirements for safety-related systems and for equipment that is intended to perform safety-related functions (functional safety) - General industrial applications

This product is intended for use in an industrial environment.

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Local Technical Support Phone Numbers	Locate the phone number for your country.	http://www.rockwellautomation.com/global/support/get-support-now.page		
Direct Dial Codes	Find the Direct Dial Code for your product. Use the code to route your call directly to a technical support engineer.	http://www.rockwellautomation.com/global/support/direct-dial.page		
Literature Library	Installation Instructions, Manuals, Brochures, and Technical Data.	http://www.rockwellautomation.com/global/literature-library/overview.page		
Product Compatibility and Download Center (PCDC)	Get help determining how products interact, check features and capabilities, and find associated firmware.	http://www.rockwellautomation.com/global/support/pcdc.page		

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